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# Optimal discretization of stochastic integrals for degenerate semimartingale 

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#### Abstract

We study the optimal discretization error of stochastic integrals, driven by a multidimensional continuous Brownian semimartingale. As a main difference compared to Gobet-Landon, Annals of Applied Probability 2014 (DOI: 10.1214/13-AAP959), the martingale part of the semimartingale may be degenerate. In this setting we establish a pathwise lower bound for the renormalized quadratic variation of the error and we provide a sequence of discretization stopping times, which is asymptotically optimal. The latter is defined as hitting times of random ellipsoids by the semimartingale at hand.


Keywords: discretization of stochastic integrals, hitting times, random ellipsoids, almost sure convergence.

MSC2010: 60G40, 60F15, 60H05.

## 1 Introduction

Statement of the problem. In this work we consider the problem of finding a finite sequence of optimal stopping times $\mathcal{T}^{n}=\left\{0=\tau_{0}^{n}<\tau_{1}^{n}<\cdots<\tau_{N_{T}^{n}}^{n}=\right.$ $T\}$ which minimizes the renormalized quadratic variation of the discretization error of the stochastic integral

$$
\begin{equation*}
Z_{s}^{n}=\int_{0}^{s} v\left(t, S_{t}\right) \cdot \mathrm{d} S_{t}-\sum_{\tau_{i-1}^{n}<s} v\left(\tau_{i-1}^{n}, S_{\tau_{i-1}^{n}}\right) \cdot\left(S_{\tau_{i}^{n} \wedge s}-S_{\tau_{i-1}^{n}}\right), \tag{1.1}
\end{equation*}
$$

[^0]where $S$ is a $d$-dimensional continuous Brownian semimartingale and $v(t, x)$ is a $\mathbb{R}^{d}$-valued continuous function. Here $T \in(0,+\infty)$ is fixed. The number of stopping times $N_{T}^{n}$ is allowed to be random.

The almost sure minimization of $Z_{T}^{n}$ is hopeless since after suitable renormalization and under some mild assumptions on the model, $Z_{T}^{n}$ weakly converges to a mixture of Gaussian random variables (see [Roo80][KP91][JP12]). Alternatively we aim at minimizing a.s. the product

$$
\begin{equation*}
N_{T}^{n}\left\langle Z^{n}\right\rangle_{T} . \tag{1.2}
\end{equation*}
$$

The choice of this minimization criterion is inspired by the fact that in many particular cases with deterministic discretization times, we have $\mathbb{E}\left(\left\langle Z^{n}\right\rangle_{T}\right) \sim$ Const/ $N_{T}^{n}$ as $N_{T}^{n} \rightarrow+\infty$.

Background results. The study of such minimization problems has been initiated by [Fuk11b] in dimension $d=1$, but instead of (1.2) the author considers a criterion in expectation for both terms, ie. $\mathbb{E}\left(N_{T}^{n}\right) \mathbb{E}\left(\left\langle Z^{n}\right\rangle_{T}\right)$. However, if $n \rightarrow+\infty$ denotes an asymptotic parameter (defined later), observe that

$$
\begin{gather*}
\liminf _{n \rightarrow+\infty} \mathbb{E}\left(N_{T}^{n}\right) \mathbb{E}\left(\left\langle Z^{n}\right\rangle_{T}\right)  \tag{1.3}\\
\text { Cauchy-Schwarz ineq. } \liminf _{n \rightarrow+\infty}^{\geq}\left[\mathbb{E}\left(\sqrt{N_{T}^{n}\left\langle Z^{n}\right\rangle_{T}}\right)\right]^{2}  \tag{1.4}\\
\underset{\text { Fatou lemma }}{\geq}\left[\mathbb{E}\left(\sqrt{\liminf _{n \rightarrow+\infty} N_{T}^{n}\left\langle Z^{n}\right\rangle_{T}}\right)\right]^{2}
\end{gather*}
$$

Since the solution to the problem of a.s. minimizing (1.2) exists (see Theorem 5.1) and is such that $N_{T}^{n}$ and $\left\langle Z^{n}\right\rangle_{T}$ are asymptotically proportional (see the limits (5.14) and (5.15)), the above inequalities can be turned into equalities (with a little of technical work) and therefore, we get for free a solution to minimizing asymptotically $\mathbb{E}\left(N_{T}^{n}\right) \mathbb{E}\left(\left\langle Z^{n}\right\rangle_{T}\right)$, however with substantially more information.

As an extra motivation for this theoretical study, we refer to the recent work of Hairer etal [HHJ15], which highlights that discretization schemes for stochastic differential equations using deterministic grid may surprisingly converge very slowly in $L_{2}$-norm. Actually any slow rate is possible [JMY15]. These amazing results give a strong incentive for studying discretization problems with stochastic grids and pathwise criterion. Applications of the current results to pathwise-optimal discretization of SDEs are left to future research.

The $\omega$-wise minimization of (1.2) has been addressed in a multi-dimensional setting $d \geq 1$, under some model conditions, in [GL14a]. In this reference, the problem is originally considered in a financial setting: $Z^{n}$ is interpreted as the hedging error of the discrete Delta-hedging strategy of an option with underlying asset $S$, maturity $T$ and price function $u\left(t, S_{t}\right)$ (then we must take $\left.v(t, x)=\nabla_{x} u(t, x)\right)$. In this case $\left(\tau_{i}^{n}\right)_{1 \leq i \leq N_{T}^{n}}$ read as trading dates. For more details on this interpretation, see [Fuk11a] and the introduction of [GL14a].

Our contributions. In the current work, we revisit the mathematical analysis of [GL14a] with significant improvements and extensions. First, we allow $S$ to be a more general Brownian semimartingale $S=A+M$, while in [GL14a] $S$ is essentially a local Brownian martingale $\left(A=0, M=\int_{0} \sigma_{s} \mathrm{~d} B_{s}\right)$. Second, the martingale part of $S$ can be degenerate in our setting, while a stronger a.s. ellipticity (on $\sigma$ ) is considered in [GL14a]. Third, we provide a strategy $\mathcal{T}^{n}$ attaining the lower bound, while in [GL14a], only a $\mu$-optimal strategy (with $\mu$ small) is designed.

The first improvement aforementioned is achieved by establishing that admissible strategies for the semimartingale $S$ and for its local martingale part $M$ are the same: see Theorem 3.4. This allows to transfer some general results of [GL14a] to our extended setting. The second improvement is important for applications and requires a quite delicate analysis. Actually the possible degeneracy lets us lose some continuity property (in particular because we need to consider the inverse $\sigma^{-1}$ ) and some convergence properties. To overcome these issues, we assume that in a sense, $\sigma_{t}$ and $D_{x} v\left(t, S_{t}\right)$ are not zero simultaneously: for a precise statement, see Assumption $\left(\mathbf{H}_{C}\right)$ or a weaker Assumption $\left(\mathbf{H}_{\Lambda}\right)$. The third improvement consists in providing an optimal strategy: we know that heuristically, the natural candidate is a sequence of hitting times by $S$ of random ellipsoids which characteristics depend on $v$ and $S$. However, in general and in particular because of the degenerate setting, this strategy is not admissible in the sense of our definitions (Section 2). Alternatively, we prove that a small perturbation makes the strategy admissible, without altering its asymptotic optimality.

Organisation of the paper. In Section 2, we define the model and the admissible strategies under study. In Section 3, we state and establish crucial properties of admissible strategies. The minimization of (1.2) is studied in Section 4, while exhibiting a optimal strategy is made in Section 5. We also present a few examples and a numerical experiment. Technical results are postponed to Appendix.

## Notation used throughout this work.

- We denote by $x \cdot y$ the scalar product between two vectors $x$ and $y$ and by $|x|=(x \cdot x)^{\frac{1}{2}}$ the Euclidean norm of $x$. The induced norm of a $m \times d$ matrix is denoted by $|A|:=\sup _{x \in \mathbb{R}^{d}:|x|=1}|A x|$.
- The transposition of a matrix $A$ is denoted by $A^{\top}$; we denote by $\operatorname{Tr}(A)$ the trace of a square matrix $A ; \mathrm{Id}_{d}$ stands for the identity matrix of size $d$.
- $\mathcal{S}^{d}(\mathbb{R}), \mathcal{S}_{+}^{d}(\mathbb{R})$ and $\mathcal{S}_{++}^{d}(\mathbb{R})$ are respectively the sets of symmetric, symmetric non-negative definite and symmetric positive-definite $d \times d$ ma-
trices with real coefficients.
- For $A \in \mathcal{S}^{d}(\mathbb{R})$ we denote $\Lambda(A)=\left(\lambda_{1}(A), \ldots, \lambda_{d}(A)\right)$ the eigenvalues of $A$ placed in decreasing order, we set $\lambda_{\min }(A):=\lambda_{d}(A)$ and $\lambda_{\max }(A):=$ $\lambda_{1}(A)$.
- We denote by $\operatorname{Diag}\left(a_{1}, \ldots, a_{d}\right)$ the square matrix of size $d$ with diagonal entries $a_{1}, \ldots, a_{d}$.
- For the partial derivatives of a function $f(t, x)$ we write

$$
D_{t} f(t, x)=\frac{\partial f}{\partial t}(t, x), D_{x_{i}} f(t, x)=\frac{\partial f}{\partial x_{i}}(t, x), D_{x_{i} x_{j}}^{2} f(t, x)=\frac{\partial^{2} f}{\partial x_{i} \partial x_{j}}(t, x) .
$$

- For a $\mathbb{R}^{d}$-valued semimartingale $S$ we denote $\langle S\rangle_{t}$ its matrix of crossvariations $\left(\left\langle S^{i}, S^{j}\right\rangle_{t}\right)_{1 \leq i, j \leq d}$.
- We sometimes write $f_{t}$ for $f\left(t, S_{t}\right)$ where $S$ is a semimartingale and $f$ is some function.
- For a given sequence of stopping times $\mathcal{T}^{n}$, the last stopping time before $t \leq T$ is defined by $\phi(t)=\max \left\{\tau_{j}^{n}: \tau_{j}^{n}<t\right\}$. We omit to indicate the dependence on $n$. Furthermore for a process $\left(f_{t}\right)_{0 \leq t \leq T}$ we write $\Delta f_{t}:=$ $f_{t}-f_{\phi(t-)}$. Besides we set $\Delta_{t}:=t-\phi(t-)$ and $\Delta \tau_{i}^{n}:=\tau_{i}^{n}-\tau_{i-1}^{n}$.
- $C_{0}$ stands for a a.s. finite non-negative random variable, which may change from line to line.


## 2 Model and strategies

### 2.1 Probabilistic model: assumptions

Let $T>0$ and let $\left(\Omega, \mathcal{F},\left(\mathcal{F}_{t}\right)_{0 \leq t \leq T}, \mathbb{P}\right)$ be a filtered probability space supporting a $d$-dimensional Brownian motion $B=\left(B^{i}\right)_{1 \leq i \leq d}$ defined on $[0, T]$, where $\left(\mathcal{F}_{t}\right)_{0 \leq t \leq T}$ is the $\mathbb{P}$-augmented natural filtration of $B$ and $\mathcal{F}=\mathcal{F}_{T}$. Let

$$
\begin{equation*}
\left(\alpha, \theta_{\sigma}\right) \in\left(\frac{1}{2}, 1\right] \times(0,1] \tag{2.1}
\end{equation*}
$$

be some regularity parameters and let $\left(S_{t}\right)_{0 \leq t \leq T}$ be a $d$-dimensional continuous semimartingale of the form

$$
\begin{equation*}
S_{t}=A_{t}+M_{t}, \quad 0 \leq t \leq T \tag{2.2}
\end{equation*}
$$

where the processes $A$ and $M$ satisfy the following hypotheses.
$\left(\mathbf{H}_{A}\right)$ The process $A$ is continuous, adapted and of finite variation, and satisfies

$$
\begin{equation*}
\left|A_{t}-A_{s}\right| \leq C_{0}|t-s|^{\alpha} \quad \forall s, t \in[0, T] \quad \text { a.s.. } \tag{A}
\end{equation*}
$$

$\left(\mathbf{H}_{M}\right)$ The process $M$ is a continuous local martingale of the form

$$
\begin{equation*}
M_{t}=\int_{0}^{t} \sigma_{s} \mathrm{~d} B_{s}, \quad 0 \leq t \leq T \tag{M}
\end{equation*}
$$

where $\sigma$ is a continuous adapted $d \times d$-matrix valued process, such that the value $\sigma_{t}$ is a.s. non-zero for any $t \in[0, T]$, and

$$
\left|\sigma_{t}-\sigma_{s}\right| \leq C_{0}|t-s|^{\theta_{\sigma} / 2} \quad \forall s, t \in[0, T] \quad \text { a.s.. }
$$

Furthermore, we assume that the function $v$, involved in (1.1), is a $\mathcal{C}^{1,2}([0, T) \times$ $\mathbb{R}^{d}$ ) function with values in $\mathbb{R}^{d}$. For applications like in [GL14a], we shall allow its derivatives in uniform norm (in space) to explode as $t \rightarrow T$, whilst remaining bounded a.s. in an infinitesimal tube centered at $\left(t, S_{t}\right)_{0 \leq t<T}$. This is stated precisely in what follows.
$\left(\mathbf{H}_{v}\right)$ Let $\mathcal{D} \in\left\{D_{x_{j}}, D_{x_{j} x_{k}}^{2}, D_{t}: 1 \leq j, k \leq d\right\}$, then

$$
\begin{equation*}
\mathbb{P}\left(\lim _{\delta \rightarrow 0} \sup _{0 \leq t<T} \sup _{\left|x-S_{t}\right| \leq \delta}|\mathcal{D} v(t, x)|<+\infty\right)=1 . \tag{v}
\end{equation*}
$$

### 2.2 Class $\mathcal{T}^{\text {adm. }}$ of admissible sequences of strategies

Now we define the class of strategies under consideration. As the optimality in our problem is achieved asymptotically as a parameter $n \rightarrow+\infty$, a strategy is naturally indexed by $n \in \mathbb{N}$ : a strategy is a finite sequence of increasing stopping times

$$
\mathcal{T}^{n}:=\left\{\tau_{0}^{n}=0<\cdots<\tau_{i}^{n}<\cdots<\tau_{N_{T}^{n}}^{n}=T\right\}, \quad \text { with } N_{T}^{n}<+\infty \text { a.s.. }
$$

We now define the appropriate asymptotic framework. Let $\left(\varepsilon_{n}\right)_{n \in \mathbb{N}}$ be a sequence of positive deterministic real numbers converging to 0 as $n \rightarrow+\infty$ and such that

$$
\sum_{n \geq 0} \varepsilon_{n}^{2}<+\infty
$$

In the following, all convergences are taken as $n \rightarrow+\infty$. The above summability enables to derive a.s. convergence results: alternatively, had we assumed only $\varepsilon_{n} \rightarrow 0$, using a subsequence-based argument (see [GL14b, Section 2.2]) we would get convergences in probability.

On the one hand the parameter $\varepsilon_{n}$ controls the oscillations of $S$ between two successive stopping times in $\mathcal{T}^{n}$.
( $\mathbf{A}_{S}^{\text {osc. }}$ ) The following non-negative random variable is a.s. finite:

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{-2} \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|S_{t}-S_{\tau_{i-1}^{n}}\right|^{2}\right)<+\infty .
$$

Here the lower argument in the assumption ( $\mathbf{A}^{\text {osc. }}$ ) refers explicitly to the process at hand. On the other hand $\varepsilon_{n}^{-2 \rho_{N}}$ (for some $\rho_{N} \geq 1$ ) upper bounds up to a constant the number of stopping times in the strategy $\mathcal{T}^{n}$.
$\left(\mathbf{A}_{N}\right)$ The following non-negative random variable is a.s. finite:

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{2 \rho_{N}} N_{T}^{n}\right)<+\infty .
$$

In the above, $\rho_{N}$ is a given parameter satisfying

$$
\begin{equation*}
1 \leq \rho_{N}<\left(1+\frac{\theta_{\sigma}}{2}\right) \wedge \frac{4}{3} \wedge\left(\frac{1}{2}+\alpha\right) \tag{2.3}
\end{equation*}
$$

where $\left(\alpha, \theta_{\sigma}\right)$ are given in (2.1).
Definition 1. A sequence of strategies $\mathcal{T}:=\left\{\mathcal{T}^{n}: n \geq 0\right\}$ is admissible for the process $S$ if it fulfills the hypotheses $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$ and $\left(\mathbf{A}_{N}\right)$. The set of admissible sequences is denoted by $\mathcal{T}_{S}^{\text {adm. }}$.

The larger $\rho_{N}$, the wider the class of strategies under consideration.

## 3 General results for admissible strategies

This section gathers preliminary results, needed to establish the subsequent main results. In Subsection 3.1, we recall without proof some estimates about the mesh size $\sup _{1 \leq i \leq N_{T}^{n}} \Delta \tau_{i}^{n}$ of the time grid $\mathcal{T}^{n}$ simultaneously for any $n$, as well as bounds on (local) martingales depending on $n$. This is preparatory for Subsection 3.2 where we establish an important result: in our setting, admissible sequences of strategies for $S$ and $M$ are the same. Last in Subsection 3.3, we establish the a.s. convergence of weighted quadratic variations under some mild assumptions, which are crucial to derive our new optimality results.

### 3.1 Control of $\Delta \tau^{n}$ and martingale increments

We start from a simple and efficient criterion for a.s. convergence of continuous local martingales.

Lemma 3.1 ([GL14a, Corollary 2.1]). Let $p>0$, and let $\left\{\left(K_{t}^{n}\right)_{0 \leq t \leq T}: n \geq 0\right\}$ be a sequence of continuous scalar local martingales vanishing at zero. Then

$$
\sum_{n \geq 0}\left\langle K^{n}\right\rangle_{T}^{p / 2}<+\infty \text { a.s. } \Longleftrightarrow \sum_{n \geq 0} \sup _{0 \leq t \leq T}\left|K_{t}^{n}\right|^{p}<+\infty \text { a.s.. }
$$

The useful application is the sense $\Rightarrow$ : by controlling the summability of quadratic variations, we obtain the non trivial a.s. convergence of $\sup _{0 \leq t \leq T}\left|K_{t}^{n}\right|$ to 0 . This kind of reasoning is used in this work.

The next two lemmas yield controls of $\Delta \tau_{i}$ and of martingales increments for an admissible sequence of strategies. In view of the Brownian motion scaling property one might guess that an admissible sequence of strategies $\mathcal{T}=\left\{\mathcal{T}^{n}: n \geq 0\right\}$ yields stopping times increments of magnitude roughly equal to $\varepsilon_{n}^{2}$. More generally, we can study in a similar way the increments of martingales. Here we give a rigorous statement of these heuristics.

Lemma 3.2 ([GL14a, Corollary 2.2]). Assume $\left(\mathrm{H}_{M}\right)$ and let $\mathcal{T}=\left\{\mathcal{T}^{n}: n \geq\right.$ $0\}$ be a sequence of strategies. Let $\rho>0$, then the following hold:
(i) Assume $\mathcal{T}$ satisfies $\left(\mathbf{A}_{M}^{\text {osc. }}\right)$, then

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{\rho-1} \sup _{1 \leq i \leq N_{T}^{n}} \Delta \tau_{i}^{n}\right)<+\infty \quad \text { a.s.. }
$$

(ii) Assume $\mathcal{T}$ satisfies $\left(\mathbf{A}_{M}^{\text {osc. }}\right)-\left(\mathbf{A}_{N}\right)$, then

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{\rho-2} \sup _{1 \leq i \leq N_{T}^{n}} \Delta \tau_{i}^{n}\right)<+\infty \quad \text { a.s.. }
$$

Lemma 3.3 ([GL14a, Corollary 2.3]). Assume $\left(\mathbf{H}_{M}\right)$. Let $\left(\left(K_{t}^{n}\right)_{0 \leq t \leq T}\right)_{n \geq 0}$ be a sequence of $\mathbb{R}^{d}$-valued continuous local martingales such that $\left\langle K^{n}\right\rangle_{t}=\int_{0}^{t} \kappa_{r}^{n} \mathrm{~d} r$ for a measurable adapted $\kappa^{n}$ satisfying the following inequality: there exist a non-negative a.s. finite random variable $C_{\kappa}$ and a deterministic parameter $\theta \geq 0$ such that

$$
0 \leq\left|\kappa_{r}^{n}\right| \leq C_{\kappa}\left(\left|\Delta M_{r}\right|^{2 \theta}+\left|\Delta_{r}\right|^{\theta}\right) \quad \forall 0 \leq r<T, \quad \forall n \geq 0, \quad \text { a.s.. }
$$

Finally, let $\rho>0$, then the following assertions hold.
(i) Assume $\mathcal{T}$ satisfies $\left(\mathbf{A}_{M}^{\text {osc. }}\right)$, then

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{\rho-(1+\theta) / 2} \sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}} \sup _{t}\left|\Delta K_{n}^{n}\right|\right)<+\infty \quad \text { a.s.. }
$$

(ii) Assume $\mathcal{T}$ satisfies $\left(\mathbf{A}_{M}^{\text {osc. }}\right)-\left(\mathbf{A}_{N}\right)$, then

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{\rho-(1+\theta)} \sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}}\left|\Delta K_{t}^{n}\right|\right)<+\infty \quad \text { a.s.. }
$$

### 3.2 The admissible sequences of strategies for $S$ and $M$ coincide

We now aim at proving the following Theorem.
Theorem 3.4. Let $S$ be a semimartingale of the form (2.2) and satisfying $\left(\mathbf{H}_{A}\right)-\left(\mathbf{H}_{M}\right)$. Then a sequence of strategies $\mathcal{T}=\left\{\mathcal{T}_{n}: n \geq 0\right\}$ is admissible for $S$ if and only it is admissible for $M$ with the same parameter $\rho_{N}$ : in other words, if $\mathcal{T}$ satisfies $\left(\mathbf{A}_{N}\right)$,

$$
\left(\mathbf{A}_{M}^{\text {osc. }}\right) \Leftrightarrow\left(\mathbf{A}_{S}^{\text {osc. }}\right)
$$

Rephrased differently, defining admissible sequence of strategies based on the martingale $M$ is robust to perturbation by adding to $M$ a finite variation process $A$, satisfying $\alpha$-Hölder regularity with $\alpha>1 / 2$.

Proof. For convenience in the proof, we adopt the short notation

$$
\left|\Delta \tau^{n}\right|_{\infty}:=\sup _{1 \leq i \leq N_{T}^{n}} \Delta \tau_{i}^{n}, \quad|\Delta U|_{\infty}:=\sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}} \sup _{1}\left|\Delta U_{t}\right|
$$

for any process $U$.
Proof of $\Rightarrow$. Suppose first that $\mathcal{T}=\left\{\mathcal{T}_{n}: n \geq 0\right\}$ is admissible for $S$. Let us prove that it is admissible for $M$, i.e. the assumption ( $\left.\mathbf{A}_{M}^{\text {osc. }}\right)$ is satisfied. We proceed in several steps.
$\triangleright$ Step 1. Preliminary bound. From $\left|M_{t}-M_{s}\right| \leq\left|S_{t}-S_{s}\right|+\left|A_{t}-A_{s}\right|$ and $\left(\mathbf{H}_{A}\right)$, we get

$$
\begin{equation*}
|\Delta M|_{\infty} \leq|\Delta S|_{\infty}+C_{0}\left|\Delta \tau^{n}\right|_{\infty}^{\alpha} \leq C_{0}\left(\varepsilon_{n}+\left|\Delta \tau^{n}\right|_{\infty}^{\alpha}\right) \tag{3.1}
\end{equation*}
$$

Using Itô's formula and $\left(\mathbf{H}_{M}\right)$, we obtain that for any $0 \leq s<t \leq T$

$$
\begin{align*}
0 \leq t-s & \leq C_{E}^{-1} \int_{s}^{t} \operatorname{Tr}\left(\sigma_{r} \sigma_{r}^{\top}\right) \mathrm{d} r=C_{E}^{-1} \sum_{j=1}^{d}\left(\left\langle S^{j}\right\rangle_{t}-\left\langle S^{j}\right\rangle_{s}\right)  \tag{3.2}\\
& =C_{E}^{-1} \sum_{j=1}^{d}\left(\left(S_{t}^{j}-S_{s}^{j}\right)^{2}-2 \int_{s}^{t}\left(S_{r}^{j}-S_{s}^{j}\right) \mathrm{d} S_{r}^{j}\right) \tag{3.3}
\end{align*}
$$

where $C_{E}:=\inf _{t \in[0, T]} \operatorname{Tr}\left(\sigma_{t} \sigma_{t}^{\top}\right)>0$ a.s.. Hence

$$
\begin{equation*}
\Delta t \leq C_{E}^{-1}\left(C_{0} \varepsilon_{n}^{2}+2 \sum_{j=1}^{d}\left|\int_{\phi(t)}^{t} \Delta S_{r}^{j} \mathrm{~d} A_{r}^{j}\right|+2 \sum_{j=1}^{d}\left|\int_{\phi(t)}^{t} \Delta S_{r}^{j} \mathrm{~d} M_{r}^{j}\right|\right) \tag{3.4}
\end{equation*}
$$

Using that $A$ is of finite variation and $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$, we get the crude estimate

$$
\begin{equation*}
\sum_{j=1}^{d}\left|\int_{\phi(t)}^{t} \Delta S_{r}^{j} \mathrm{~d} A_{r}^{j}\right| \leq C_{0} \varepsilon_{n} \tag{3.5}
\end{equation*}
$$

Now consider the local martingale $K_{t}^{n, j}=\varepsilon_{n}^{\frac{2}{p}-1}\left(\int_{0}^{t} \Delta S_{r}^{j} \mathrm{~d} M_{r}^{j}\right)$ for some $p>0$. We have

$$
\sum_{n \geq 0}\left\langle K^{n, j}\right\rangle_{T}^{\frac{p}{2}}=\sum_{n \geq 0} \varepsilon_{n}^{2-p}\left(\int_{0}^{T}\left|\Delta S_{r}^{j}\right|^{2} \mathrm{~d}\left\langle M^{j}\right\rangle_{r}\right)^{\frac{p}{2}} \leq C_{0} \sum_{n \geq 0} \varepsilon_{n}^{2}<+\infty \quad \text { a.s. }
$$

which by Lemma 3.1 implies that $\sum_{n \geq 0} \sup _{0 \leq t \leq T}\left|K_{t}^{n, j}\right|^{p}<+\infty$ a.s., and thus $\sup _{n \geq 0} \sup _{0 \leq t \leq T}\left|K_{t}^{n, j}\right|<+\infty$ a.s.. This reads

$$
\begin{equation*}
\sup _{0 \leq t \leq T}\left|\int_{0}^{t} \Delta S_{r}^{j} \mathrm{~d} M_{r}^{j}\right| \leq C_{0} \varepsilon_{n}^{1-\frac{2}{p}}=C_{0} \varepsilon_{n}^{1-\delta} \tag{3.6}
\end{equation*}
$$

where $\delta=2 / p$ is an arbitrary positive number. Plugging this and (3.5) into (3.4) yields

$$
\begin{equation*}
\left|\Delta \tau^{n}\right|_{\infty} \leq C_{0}\left(\varepsilon_{n}^{2}+\varepsilon_{n}+\varepsilon_{n}^{1-\delta}\right) \leq C_{0} \varepsilon_{n}^{1-\delta} . \tag{3.7}
\end{equation*}
$$

The above is analogous to Lemma 3.2-(i) but under the assumption ( $\mathbf{A}_{S}^{\text {osc. }}$ ). Combined with (3.1), we then deduce

$$
\begin{equation*}
|\Delta M|_{\infty} \leq C_{0} \varepsilon_{n}^{\alpha(1-\delta)} \tag{3.8}
\end{equation*}
$$

for any given $\delta \in(0,1)$.
$\triangleright$ Step 2. We prove the following lemma, which gives the basis for a continuation argument (Step 3): once we have estimated $|\Delta M|_{\infty}$ with some order w.r.t. $\varepsilon_{n}$, we obtain automatically a slightly better order, up to reaching the order 1, as required by ( $\left.\mathbf{A}_{M}^{\text {osc. }}\right)$.
Lemma 3.5. Suppose that for some $\beta>0$

$$
\begin{equation*}
\sup _{n \geq 0}\left(\varepsilon_{n}^{-\beta} \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\Delta M_{t}\right|^{2}\right)<+\infty \quad \text { a.s.. } \tag{3.9}
\end{equation*}
$$

Then for any $\rho>0$

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{-(\beta-\rho)} \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\sum_{j=1}^{d} \Delta\left\langle M^{j}\right\rangle_{t}\right|\right)<+\infty \quad \text { a.s.. }
$$

Proof. Let $p>0$. Consider the following two sequences of processes:

$$
\begin{aligned}
& U_{t}^{n}=\varepsilon_{n}^{2-\beta p+2 \rho_{N}} \sum_{\tau_{i-1}^{n}<t}\left|\sum_{j=1}^{d} \Delta\left\langle M^{j}\right\rangle_{\tau_{i}^{n} \wedge t}\right|^{p} \\
& V_{t}^{n}=\varepsilon_{n}^{2-\beta p+2 \rho_{N}} \sum_{\tau_{i-1}^{n}<t} \sup _{s \in\left(\tau_{i-1}^{n}, \tau_{i}^{n} \wedge t\right]}\left|\Delta M_{s}\right|^{2 p} .
\end{aligned}
$$

We aim at proving that $\sum_{n \geq 0} U_{T}^{n}<+\infty$ a.s. using Lemma A. 1 in Appendix. First, $\sum_{n \geq 0} V_{T}^{n}$ converges a.s.: indeed using $\left(\mathbf{A}_{N}\right)$ and (3.9) we obtain

$$
\sum_{n \geq 0} V_{T}^{n} \leq C_{0} \sum_{n \geq 0} \varepsilon_{n}^{2-\beta p+2 \rho_{N}} N_{T}^{n} \sup _{1 \leq i \leq N_{T}^{n}} \sup _{s \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\Delta M_{s}\right|^{2 p} \leq C_{0} \sum_{n \geq 0} \varepsilon_{n}^{2}<+\infty .
$$

Second observe that for any $n, t \mapsto V_{t}^{n}$ is a.s. non-decreasing. Last it remains to verify the relation of domination of Lemma A.1-(iii). Let $k \in \mathbb{N}$, let $\theta_{k}$ be defined as in the quoted lemma. On the set $\left\{\tau_{i-1}^{n}<t \wedge \theta_{k}\right\}$ from a conditional version of the multidimensional BDG inequality we have

$$
\mathbb{E}\left(\left|\sum_{j=1}^{d} \Delta\left\langle M^{j}\right\rangle_{\tau_{i}^{n} \wedge t \wedge \theta_{k}}\right|^{p} \mid \mathcal{F}_{\tau_{i-1}^{n}}\right) \leq c_{p} \mathbb{E}\left(\sup _{\tau_{i-1}^{n}<s \leq \tau_{i}^{n} \wedge t \wedge \theta_{k}}\left|\Delta M_{s}\right|^{2 p} \mid \mathcal{F}_{\tau_{i-1}^{n}}\right) .
$$

Then it follows that

$$
\begin{aligned}
\mathbb{E}\left(U_{t \wedge \theta_{k}}^{n}\right) & =\varepsilon_{n}^{2-\beta p+2 \rho_{N}} \sum_{i=1}^{+\infty} \mathbb{E}\left(1_{\tau_{i-1}^{n}<t \wedge \theta_{k}} \mathbb{E}\left(\left|\sum_{j=1}^{d} \Delta\left\langle M^{j}\right\rangle_{\tau_{i}^{n} \wedge t \wedge \theta_{k}}\right|^{p} \mid \mathcal{F}_{\tau_{i-1}^{n}}\right)\right) \\
& \leq c_{p} \mathbb{E}\left(V_{t \wedge \theta_{k}}^{n}\right) .
\end{aligned}
$$

Hence by Lemma A.1, we obtain that $\sum_{n \geq 0} U_{T}^{n}$ converges a.s. and thus $\sup _{n \geq 0} U_{T}^{n}<$ $+\infty$ a.s..

Now write $\varepsilon_{n}^{2-\beta p+2 \rho_{N}} \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\sum_{j=1}^{d} \Delta\left\langle M^{j}\right\rangle_{t}\right|^{p} \leq U_{T}^{n}$, which implies

$$
\sup _{n \geq 0}\left(\varepsilon_{n}^{\left(2+2 \rho_{N}\right) / p-\beta} \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\sum_{j=1}^{d} \Delta\left\langle M^{j}\right\rangle_{t}\right|\right)<+\infty \quad \text { a.s.. }
$$

To conclude, choose $p=\frac{2+2 \rho_{N}}{\rho}$ to get the desired result.
$\triangleright$ Step 3. Continuation scheme. Take $\delta>0$, as in (3.8), set $d_{0}=\alpha(1-\delta)$ and $\rho_{0}=\frac{(2 \alpha-1) d_{0}}{2 \alpha}>0$. Consider the sequence $\left(d_{m}\right)_{m \geq 0}$ given by $d_{m+1}=$ $2 \alpha d_{m}-\alpha \rho_{0}$ for $m \geq 0$. Assume for a while that

$$
\begin{equation*}
d_{m+1}-d_{m} \geq \alpha \rho_{0} \tag{3.10}
\end{equation*}
$$

and let us show by induction that, for any $m \geq 0$,

$$
\begin{equation*}
|\Delta M|_{\infty} \leq C_{0} \varepsilon_{n}^{\min \left(d_{m}, 1\right)} . \tag{3.11}
\end{equation*}
$$

The case $m=0$ stems directly from (3.8). Now suppose that (3.11) holds for $m$. If $d_{m} \geq 1$, since $d_{m+1} \geq d_{m}$ owing to (3.10), (3.11) is valid for $m+1$. If $d_{m}<1$, then we have $|\Delta M|_{\infty} \leq C_{0} \varepsilon_{n}^{d_{m}}$ and using Lemma 3.5 we obtain

$$
\left|\sum_{j=1}^{d} \Delta\left\langle M^{j}\right\rangle\right|_{\infty} \leq C_{0} \varepsilon_{n}^{2 d_{m}-\rho_{0}}
$$

Consequently (3.2) gives $\left|\Delta \tau^{n}\right|_{\infty} \leq C_{0} \varepsilon_{n}^{2 d_{m}-\rho_{0}}$ which, combined with (3.1), yields

$$
|\Delta M|_{\infty} \leq C_{0} \varepsilon_{n}^{\min \left(1, \alpha\left(2 d_{m}-\rho_{0}\right)\right)}
$$

This finishes the proof of (3.11) for $m+1$. It remains to show (3.10) by induction. For $m=0$ we get $d_{1}=2 \alpha d_{0}-\alpha \rho_{0}$ and thus

$$
d_{1}-d_{0}=(2 \alpha-1) d_{0}-\frac{(2 \alpha-1) d_{0}}{2}=\frac{(2 \alpha-1) d_{0}}{2}=\alpha \rho_{0} .
$$

Suppose that (3.10) is true for all $m<k$ and let us extend to $m=k$. We write

$$
d_{m+1}-d_{m}=(2 \alpha-1) d_{m}-\frac{(2 \alpha-1) d_{0}}{2} \geq(2 \alpha-1) d_{0}-\frac{(2 \alpha-1) d_{0}}{2}=\alpha \rho_{0}
$$

using that $d_{m} \geq d_{0}$ by the induction assumption. We are done.
$\triangleright$ Step 4. Conclusion. In view of (3.10), $\left(d_{m}\right)_{m \geq 0}$ becomes larger than 1 for some $m$, for which (3.11) simply writes $|\Delta M|_{\infty} \leq C_{0} \varepsilon_{n} .\left(\mathbf{A}_{M}^{\text {osc. }}\right)$ is proved.

Proof of $\Leftarrow$. Now suppose that the sequence $\mathcal{T}$ is admissible for $M$. Let us prove the admissibility of $\mathcal{T}$ for the process $S$. Again it is enough to verify the assumption ( $\mathbf{A}_{S}^{\text {osc. }}$ ). Similarly to the decomposition (3.1), we have

$$
|\Delta S|_{\infty} \leq|\Delta M|_{\infty}+|\Delta A|_{\infty} \leq C_{0}\left(\varepsilon_{n}+\left|\Delta \tau^{n}\right|_{\infty}^{\alpha}\right)
$$

From Lemma 3.2-(ii), for any $\gamma>0$, we have $\left|\Delta \tau^{n}\right|_{\infty} \leq C_{0} \varepsilon_{n}^{2-\gamma}$ a.s.. Since $\alpha>1 / 2$, we can choose $\gamma$ such that $(2-\gamma) \alpha>1$ and for such $\gamma$ we deduce $|\Delta S|_{\infty} \leq C_{0}\left(\varepsilon_{n}+\varepsilon_{n}^{(2-\gamma) \alpha}\right) \leq C_{0} \varepsilon_{n}$. The proof is complete.

## Remark 1.

- Theorem 3.4 implies that if a sequence of strategies fulfills $\left(\mathbf{A}_{N}\right)$, we do not need to emphasize anymore the dependence of the assumption ( $\mathbf{A}^{\text {osc. }}$ ) on a particular process $M$ or $S$; in that case, we will write simply ( $\mathbf{A}^{\text {osc. }}$ ) and will refer to admissible sequence of strategies $\mathcal{T}^{\text {adm. }}:=\mathcal{T}_{M}^{\text {adm. }}=$ $\mathcal{T}_{S}^{\text {adm }}$.
- In addition, we can use all the results for admissible sequences of strategies based on the local martingale $M$ and ( $\left.\mathbf{A}_{M}^{\text {osc. }}\right)$ (as those from [GL14a]): in particular, for any admissible sequences of strategies (for $M$ or $S$ ), we have $\sup _{1 \leq i \leq N_{T}^{n}}\left|\Delta \tau_{i}^{n}\right| \leq C_{0} \varepsilon_{n}^{2-\gamma}$ for any $\gamma>0$.
A direct consequence of Lemma 3.2-(ii), $\left(\mathbf{H}_{A}\right)$ and Theorem 3.4 is the following.
Corollary 3.6. Let $S$ be a semimartingale of the form (2.2) and satisfying $\left(\mathbf{H}_{A}\right)-\left(\mathbf{H}_{M}\right)$. If $\mathcal{T} \in \mathcal{T}^{\text {adm. }}$, then for any $\rho>0$,

$$
\sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}} \sup _{t}\left|\Delta A_{t}\right| \leq C_{0} \varepsilon_{n}^{2 \alpha-\rho} .
$$

### 3.3 Convergence results for quadratic variation

We first recall a convergence result about weighted discrete quadratic $M$ variations corresponding to $\mathcal{T}=\left\{\mathcal{T}^{n}, n \geq 0\right\}$.

Proposition 3.7. [GL14a, Proposition 2.3] Assume $\left(\mathbf{H}_{M}\right)$ and let $\mathcal{T}$ be a sequence of strategies satisfying $\left(\mathbf{A}_{M}^{\text {osc. }}\right)$. Let $\left(H_{t}\right)_{0 \leq t<T}$ be a continuous adapted $d \times d$-matrix process such that $\sup _{t \in[0, T)}\left|H_{t}\right|<+\infty$ a.s., and let $\left(K_{t}\right)_{0 \leq t \leq T}$ be a $\mathbb{R}^{d}$-valued continuous local martingale such that $\langle K\rangle_{t}=\int_{0}^{t} \kappa_{r} \mathrm{~d} r$ with $\sup _{t \in[0, T]}\left|\kappa_{t}\right|<+\infty$ a.s.. Then

$$
\sum_{\tau_{i-1}^{n}<T} \Delta K_{\tau_{i}^{n}}^{\top} H_{\tau_{i-1}^{n}} \Delta K_{\tau_{i}^{n}} \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(H_{t} \mathrm{~d}\langle K\rangle_{t}\right) .
$$

We now establish an extension to the semimartingale $S$.
Proposition 3.8. Let $S$ be a semimartingale of the form (2.2) and satisfying $\left(\mathbf{H}_{A}\right)-\left(\mathbf{H}_{M}\right)$, and let $\mathcal{T}$ be a sequence of strategies satisfying $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$. Let $\left(H_{t}\right)_{0 \leq t<T}$ as in Proposition 3.7. Then

$$
\sum_{\tau_{i-1}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} H_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}} \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(H_{t} \mathrm{~d}\langle M\rangle_{t}\right) .
$$

Proof. From Itô's lemma, the difference between the above left hand side and the right one is equal to

$$
\begin{equation*}
\int_{0}^{T} \Delta S_{t}^{\top}\left(H_{\varphi(t)}+H_{\varphi(t)}^{\top}\right) \mathrm{d} S_{t}+\int_{0}^{T} \operatorname{Tr}\left(\left[H_{\varphi(t)}-H_{t}\right] \mathrm{d}\langle M\rangle_{t}\right) \tag{3.12}
\end{equation*}
$$

Due to $\left(\mathbf{H}_{M}\right)$, the second term is bounded by $C_{0} \int_{0}^{T}\left|H_{\varphi(t)}-H_{t}\right| \mathrm{d} t$ : it converges to 0 by an application of the dominated convergence theorem. Indeed, $H$ is continuous and bounded on $[0, T)$ and the mesh size goes to 0 under ( $\mathbf{A}_{S}^{\text {osc. }}$ ) (see (3.7) which is established under ( $\mathbf{A}_{S}^{\text {osc. }}$ ) and without using $\left(\mathbf{A}_{N}\right)$ ). Next, decompose the first term of (3.12) into stochastic integrals w.r.t. $A$ and $M$. On the one hand, $A$ is of finite variation, thus

$$
\begin{equation*}
\left|\int_{0}^{T} \Delta S_{t}^{\top}\left(H_{\varphi(t)}+H_{\varphi(t)}^{\top}\right) \mathrm{d} A_{t}\right| \leq C_{0} \sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}} \sup _{t}\left|\Delta S_{t}\right| \sup _{t \in[0, T)}\left|H_{t}\right| \xrightarrow{\text { a.s. }} 0 \tag{3.13}
\end{equation*}
$$

in view of $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$. On the other hand, $\int_{0}^{T} \Delta S_{t}^{\boldsymbol{\top}}\left(H_{\varphi(t)}+H_{\varphi(t)}^{\top}\right) \mathrm{d} M_{t} \xrightarrow{\text { a.s. }} 0$ by proceeding very similarly to the proof of (3.6).

In the next theorems we identify an important admissible sequence of strategies, namely hitting times by $S$ of random ellipsoids parametrized by a matrix process $\left(H_{t}\right)_{0 \leq t<T}$ (or a perturbation of it). This extends [GL14a, Proposition 2.4] to hitting times of $S$ and to possibly degenerate $H$. This more general construction of ellipsoids is a significant improvement, and crucial for the subsequent optimality results.

Theorem 3.9. Let $S$ be a semimartingale of the form (2.2) and satisfying $\left(\mathbf{H}_{A}\right)-\left(\mathbf{H}_{M}\right)$, and let $\left(H_{t}\right)_{0 \leq t<T}$ be a continuous adapted symmetric nonnegative definite $d \times d$ matrix process, such that a.s.

$$
0<\inf _{0 \leq t<T} \lambda_{\min }\left(H_{t}\right) \leq \sup _{0 \leq t<T} \lambda_{\max }\left(H_{t}\right)<+\infty
$$

The strategy $\mathcal{T}^{n}$ given by

$$
\left\{\begin{array}{l}
\tau_{0}^{n}:=0 \\
\tau_{i}^{n}:=\inf \left\{t>\tau_{i-1}^{n}:\left(S_{t}-S_{\tau_{i-1}^{n}}\right)^{\top} H_{\tau_{i-1}^{n}}\left(S_{t}-S_{\tau_{i-1}^{n}}\right) \geq \varepsilon_{n}^{2}\right\} \wedge T
\end{array}\right.
$$

defines a admissible sequence of strategies.
The proof is given later. The condition $\sup _{0 \leq t<T} \lambda_{\max }\left(H_{t}\right)<+\infty$ ensures that none of the corresponding ellipsoids $\mathcal{E}_{t}:=\left\{x^{\top} H_{t} x \leq c\right\}$ with $c>0$ are flat in some directions, it allows to derive a bound on the number of hitting times $N_{T}^{n}$ as in $\left(\mathbf{A}_{N}\right)$. The non-degeneracy condition $\lambda_{\min }\left(H_{t}\right)>0$ (i.e. $\mathcal{E}_{t}$ is bounded) is important to control the increments $\Delta S$ as in ( $\left.\mathbf{A}_{S}^{\text {osc. }}\right)$. Without this latter condition, we need to perturb the above sequence of strategies. To this purpose, let $\chi($.$) be a smooth function such that$

$$
\begin{equation*}
\mathbf{1}_{(-\infty, 1 / 2]} \leq \chi(.) \leq \mathbf{1}_{(-\infty, 1]} \tag{3.14}
\end{equation*}
$$

and for $\mu>0$ set $\chi_{\mu}(x)=\chi(x / \mu)$.
Theorem 3.10. Let $S$ be a semimartingale of the form (2.2) and satisfying $\left(\mathbf{H}_{A}\right)-\left(\mathbf{H}_{M}\right)$. Assume that $\rho_{N}$ defined in (2.3) is such that $\rho_{N}>1$, and let $\delta \in\left(0,2\left(\rho_{N}-1\right)\right]$. Let $\left(H_{t}\right)_{0 \leq t<T}$ be an adapted symmetric non-negative definite $d \times d$ matrix process, such that
(i) there exists a random variable $C_{H}$, positive and finite a.s., such that

$$
\lambda_{\max }\left(H_{t}\right) \leq C_{H}, \quad \forall t \in[0, T), \quad \text { a.s.. }
$$

(notice that $H$ is not necessarily continuous).
Define a sequence of processes $H^{n}$ by

$$
H_{t}^{(n)}=H_{t}+\varepsilon_{n}^{\delta} \chi_{\varepsilon_{n}^{\delta}}\left(\lambda_{\min }\left(H_{t}\right)\right) \operatorname{Id}_{d}
$$

Then the strategy $\mathcal{T}^{n}$ defined by

$$
\left\{\begin{array}{l}
\tau_{0}^{n}:=0  \tag{3.15}\\
\tau_{i}^{n}:=\inf \left\{t>\tau_{i-1}^{n}:\left(S_{t}-S_{\tau_{i-1}^{n}}\right)^{\top} H_{\tau_{i-1}^{n}}^{(n)}\left(S_{t}-S_{\tau_{i-1}^{n}}\right) \geq \varepsilon_{n}^{2+\delta}\right\} \wedge T,
\end{array}\right.
$$

forms a sequence $\mathcal{T}=\left\{\mathcal{T}^{n}: n \geq 0\right\}$ satisfying the assumption $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$. If in addition the following convergence holds
(ii)

$$
\sum_{\tau_{i-1}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} H_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}} \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(H_{t} \mathrm{~d}\langle M\rangle_{t}\right),
$$

then the sequence $\mathcal{T}$ satisfies also the assumption $\left(\mathbf{A}_{N}\right)$, that is $\mathcal{T} \in \mathcal{T}^{\text {adm. }}$.
Proof of Theorem 3.10. First let us prove that $\mathcal{T}_{n}$ is a.s. of finite size for any $n \in \mathbb{N}$. The definition of $H_{t}^{n}$ implies that

$$
\lambda_{\max }\left(H_{t}^{(n)}\right) \leq C_{H}+\sup _{n \geq 0} \varepsilon_{n}^{\delta}<+\infty, \quad \forall t \in[0, T) \quad \text { a.s.. }
$$

Define the event $\mathcal{N}^{n}:=\left\{\omega: N_{T}^{n}(\omega)=+\infty\right\}$. For $\omega \in \mathcal{N}^{n}$ the infinite sequence $\left(\tau_{i}^{n}(\omega)\right)$ is increasing and bounded, thus converges. Hence on $\mathcal{N}^{n} \cap E_{S}$, with

$$
E_{S}=\left\{\left(S_{t}\right)_{t \in[0, T]} \text { is continuous and } C_{H}<+\infty\right\}
$$

we have

$$
\begin{aligned}
0<\varepsilon_{n}^{2+\delta} & =\left(S_{\tau_{i}^{n}}-S_{\tau_{i-1}^{n}}\right)^{\top} H_{\tau_{i-1}^{n}}^{n}\left(S_{\tau_{i}^{n}}-S_{\tau_{i-1}^{n}}\right) \\
& \leq\left(C_{H}+\sup _{n \geq 0} \varepsilon_{n}^{\delta}\right)\left|S_{\tau_{i}^{n}}-S_{\tau_{i-1}^{n}}\right|^{2} \xrightarrow{i \rightarrow+\infty} 0,
\end{aligned}
$$

which is impossible. Hence $\mathbb{P}\left(\mathcal{N}^{n} \cap E_{S}\right)=0$, but $\mathbb{P}\left(E_{S}\right)=1$ thus $\mathbb{P}\left(\mathcal{N}^{n}\right)=0$.
Next we show that $\mathcal{T}$ satisfies $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$. From the definition of $H_{t}^{(n)}$ it is straightforward that

$$
\lambda_{\min }\left(H_{t}^{(n)}\right) \geq \frac{\varepsilon_{n}^{\delta}}{2}, \quad \forall t \in[0, T)
$$

Thus

$$
\begin{aligned}
& \varepsilon_{n}^{-2} \sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}}\left|\Delta S_{t}\right|^{2} \\
& \leq\left(\inf _{t \in[0, T)} \lambda_{\min }\left(H_{t}^{(n)}\right)\right)^{-1} \varepsilon_{n}^{-2} \sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}} \sup _{t}\left(\Delta S_{t}^{\top} H_{t}^{(n)} \Delta S_{t}\right) \leq 2 \varepsilon_{n}^{-\delta} \varepsilon_{n}^{-2} \varepsilon_{n}^{2+\delta}=2,
\end{aligned}
$$

which validates the assumption ( $\left.\mathbf{A}_{S}^{\text {osc. }}\right)$.

Finally assume that in addition (ii) holds and let us show that the sequence of strategies $\mathcal{T}$ satisfies the assumption $\left(\mathbf{A}_{N}\right)$. Writing $N_{T}^{n}=1+\sum_{1 \leq i \leq N_{T}^{n}-1} 1$ and using $2+\delta \leq 2 \rho_{N}$, we observe that (for $n$ large enough so that $\varepsilon_{n} \leq 1$ )

$$
\begin{equation*}
\varepsilon_{n}^{2 \rho_{N}} N_{T}^{n} \leq \varepsilon_{n}^{2+\delta} N_{T}^{n} \leq \varepsilon_{n}^{2+\delta}+\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} H_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}+\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top}\left(H_{\tau_{i-1}^{n}}^{(n)}-H_{\tau_{i-1}^{n}}\right) \Delta S_{\tau_{i}^{n}} \tag{3.16}
\end{equation*}
$$

Now by (ii) we have

$$
\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} H_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}} \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(H_{t} \mathrm{~d}\langle M\rangle_{t}\right) \stackrel{\text { a.s. }}{<}+\infty
$$

(the contribution $i=N_{T}^{n}$ does not change the convergence). Besides from the definition of $H^{(n)}$ we get

$$
\begin{equation*}
\left|\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top}\left(H_{\tau_{i-1}^{n}}^{(n)}-H_{\tau_{i-1}^{n}}\right) \Delta S_{\tau_{i}^{n}}\right| \leq \varepsilon_{n}^{\delta} \sum_{\tau_{i}^{n}<T}\left|\Delta S_{\tau_{i}^{n}}\right|^{2} \xrightarrow{\text { a.s. }} 0, \tag{3.17}
\end{equation*}
$$

using $\delta>0$ and Proposition 3.8 (valid since ( $\mathbf{A}_{S}^{\text {osc. }}$ ) is in force now). We have proved that the r.h.s. of (3.16) converges a.s. to a finite random variable, which completes the verification of the assumption $\left(\mathbf{A}_{N}\right)$.

Proof of Theorem 3.9. This is an adaptation of the previous proof. First, with the same arguments we prove that $\mathcal{T}_{n}$ is a.s. of finite size for any $n \in \mathbb{N}$. Second, the verification of $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$ stems from

$$
\varepsilon_{n}^{-2} \sup _{1 \leq i \leq N_{T}^{n} \tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}} \sup _{t}\left|\Delta S_{t}\right|^{2} \leq\left(\inf _{t \in[0, T)} \lambda_{\min }\left(H_{t}\right)\right)^{-1}
$$

Third, for $n$ large enough so that $\varepsilon_{n} \leq 1$, we write

$$
\varepsilon_{n}^{2 \rho_{N}} N_{T}^{n} \leq \varepsilon_{n}^{2} N_{T}^{n} \leq \varepsilon_{n}^{2}+\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} H_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}
$$

and we conclude to $\left(\mathbf{A}_{N}\right)$ using Proposition 3.8 and the continuity and boundedness of $H$.

## 4 Asymptotic lower bound on the discretization error

Let $S$ be a semimartingale of the form (2.2) and let $v$ be the function appearing in the discretization error (1.1), and satisfying $\left(\mathbf{H}_{v}\right)$. The main result of the
section is Theorem 4.2: this is an extension to the semimartingale case of the asymptotic lower bound on the discretization error, proved in [GL14a, Theorem 3.1] in the martingale case.

The discretization error $Z^{n}$ defined in (1.1) can be decomposed into a martingale part and a finite variation part:

$$
Z_{s}^{n}=\int_{0}^{s}\left(v\left(t, S_{t}\right)-v\left(\phi(t), S_{\phi(t)}\right)\right) \cdot \mathrm{d} M_{t}+\int_{0}^{s}\left(v\left(t, S_{t}\right)-v\left(\phi(t), S_{\phi(t)}\right)\right) \cdot \mathrm{d} A_{t}
$$

The analysis is partially derived from a smart representation of $\left\langle Z^{n}\right\rangle_{T}$ as a sum of squared random variables and an adequate application of CauchySchwarz inequality. The derivation of such a representation is based on applying the Itô formula to a suitable function and identifying the bounded variation term. While it is straightforward in dimension one, a multidimensional version of this result requires to solve the following matrix equation.
Lemma 4.1. Let c be a $d \times d$-matrix with real-valued entries. Then the equation

$$
\begin{equation*}
2 \operatorname{Tr}(x) x+4 x^{2}=c c^{\top} \tag{4.1}
\end{equation*}
$$

admits exactly one solution $x(c) \in \mathcal{S}_{+}^{d}(\mathbb{R})$. Moreover, the mapping $c \mapsto x(c)$ is continuous.

The proof of the above lemma directly follows from [GL14a, Lemma 3.1] applied for $\left(c c^{\top}\right)^{1 / 2}$ (i.e. the symmetric non-negative definite square root of $c c^{\top}$ ). Now we state the main result.
Theorem 4.2 (Lower bound). Assume $\left(\mathbf{H}_{A}\right),\left(\mathbf{H}_{M}\right),\left(\mathbf{H}_{v}\right)$ and let $\mathcal{T}$ be an admissible sequence of strategies (satisfying $\left(\mathbf{A}_{N}\right)$ and $\left.\left(\mathbf{A}^{\text {osc. }}\right)\right)$. Let $X$ be the continuous adapted symmetric non-negative definite matrix process solution of (4.1) with $c=\sigma^{\top}\left(D_{x} v\right)^{\top} \sigma$, i.e.

$$
\begin{equation*}
X_{t}:=x\left(\sigma_{t}^{\top}\left(D_{x} v_{t}\right)^{\top} \sigma_{t}\right), \quad \text { for } \quad 0 \leq t<T \tag{4.2}
\end{equation*}
$$

Then we have

$$
\liminf _{n \rightarrow+\infty} N_{T}^{n}\left\langle Z^{n}\right\rangle_{T} \geq\left(\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t\right)^{2} \quad \text { a.s. }
$$

Proof. The martingale part of the discretization error can be written

$$
\begin{equation*}
\int_{0}^{s}\left(v\left(t, S_{t}\right)-v\left(\phi(t), S_{\phi(t)}\right)\right) \cdot \mathrm{d} M_{t}=: \int_{0}^{s}\left(D_{x} v_{\phi(t)} \Delta S_{t}\right) \mathrm{d} M_{t}+R_{s}^{n} \tag{4.3}
\end{equation*}
$$

Therefore the quadratic variation of $Z^{n}$ is given by

$$
\begin{align*}
\left\langle Z^{n}\right\rangle_{T} & =\int_{0}^{T} \Delta S_{t}^{\top}\left(D_{x} v_{\phi(t)}\right)^{\top} \mathrm{d}\langle M\rangle_{t} D_{x} v_{\phi(t)} \Delta S_{t}+e_{1, T}^{n} \\
& =\int_{0}^{T} \Delta M_{t}^{\top}\left(D_{x} v_{\phi(t)}\right)^{\top} \mathrm{d}\langle M\rangle_{t} D_{x} v_{\phi(t)} \Delta M_{t}+e_{1, T}^{n}+e_{0, T}^{n} \tag{4.4}
\end{align*}
$$

where

$$
\begin{aligned}
& e_{0, T}^{n}:=\int_{0}^{T} \Delta A_{t}^{\top}\left(D_{x} v_{\phi(t)}\right)^{\top} \mathrm{d}\langle M\rangle_{t} D_{x} v_{\phi(t)}\left(\Delta S_{t}+\Delta M_{t}\right), \\
& e_{1, T}^{n}:=\left\langle R^{n}\right\rangle_{T}+2\left\langle\int_{0}\left(D_{x} v_{\phi(t)} \Delta M_{t}\right) \cdot \mathrm{d} M_{t}, R^{n}\right\rangle_{T}
\end{aligned}
$$

Now in the first contribution of $\left\langle Z^{n}\right\rangle_{T}$ in (4.4), we seek an expression involving only the Brownian motion $B$ and not the local martingale $M$ : hence we replace $\Delta M_{t}$ by $\sigma_{\phi(t)} \Delta B_{t}$ and $\mathrm{d}\langle M\rangle_{t}$ by $\sigma_{\phi(t)} \sigma_{\phi(t)}^{\top} \mathrm{d} t$, which leads to

$$
\left\langle Z^{n}\right\rangle_{T}=\int_{0}^{T} \Delta B_{t}^{\top}\left(\sigma_{\phi(t)}^{\top}\left(D_{x} v_{\phi(t)}\right)^{\top} \sigma_{\phi(t)} \sigma_{\phi(t)}^{\top} D_{x} v_{\phi(t)} \sigma_{\phi(t)}\right) \Delta B_{t} \mathrm{~d} t+e_{0, T}^{n}+e_{1, T}^{n}+e_{2, T}^{n},
$$

where

$$
\begin{aligned}
e_{2, T}^{n}:= & \int_{0}^{T} \Delta M_{t}^{\top}\left(D_{x} v_{\phi(t)}\right)^{\top} \Delta\left(\sigma_{t} \sigma_{t}^{\top}\right) D_{x} v_{\phi(t)} \Delta M_{t} \mathrm{~d} t \\
& +\int_{0}^{T}\left(\Delta M_{t}+\sigma_{\phi(t)} \Delta B_{t}\right)^{\top}\left(D_{x} v_{\phi(t)}\right)^{\top} \sigma_{\phi(t)} \sigma_{\phi(t)}^{\top} D_{x} v_{\phi(t)}\left(\Delta M_{t}-\sigma_{\phi(t)} \Delta B_{t}\right) \mathrm{d} t .
\end{aligned}
$$

Denote $C_{t}=\sigma_{t}^{\top}\left(D_{x} v_{t}\right)^{\top} \sigma_{t}$. We seek a smart representation of the main term of $\left\langle Z^{n}\right\rangle_{T}$ in the form

$$
\begin{equation*}
\sum_{\tau_{i-1}^{n}<T}\left(\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}\right)^{2}, \tag{4.5}
\end{equation*}
$$

where $X$ is a suitable measurable adapted symmetric $d \times d$-matrix process. For such a process $X$, the Itô formula on each interval $\left[\tau_{i-1}^{n}, \tau_{i}^{n}\right]$ yields

$$
\begin{aligned}
\sum_{\tau_{i-1}^{n}<T}\left(\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}\right)^{2} & =\int_{0}^{T} \Delta B_{t}^{\top}\left(2 \operatorname{Tr}\left(X_{\phi(t)}\right) X_{\phi(t)}+4 X_{\phi(t)}^{2}\right) \Delta B_{t} \mathrm{~d} t \\
& +4 \int_{0}^{T} \Delta B_{t}^{\top} X_{\phi(t)} \Delta B_{t} \Delta B_{t}^{\top} X_{\phi(t)} \mathrm{d} B_{t}
\end{aligned}
$$

Now take $X$ as stated in the theorem. Clearly $X_{t} \in \mathcal{S}_{+}^{d}(\mathbb{R})$ owing to Lemma 4.1. The continuity of the mapping $c \mapsto x(c)$ also ensures that $X$ is continuous and adapted, as $\sigma^{\top}\left(D_{x} v\right)^{\top} \sigma$ is. Then a simplified representation of $\left\langle Z^{n}\right\rangle_{T}$ readily follows:

$$
\begin{equation*}
\left\langle Z^{n}\right\rangle_{T}=\sum_{\tau_{i-1}^{n}<T}\left(\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}\right)^{2}+e_{0, T}^{n}+e_{1, T}^{n}+e_{2, T}^{n}+e_{3, T}^{n}, \tag{4.6}
\end{equation*}
$$

where

$$
e_{3, T}^{n}:=-4 \int_{0}^{T} \Delta B_{t}^{\top} X_{\phi(t)} \Delta B_{t} \Delta B_{t}^{\top} X_{\phi(t)} \mathrm{d} B_{t} .
$$

Using Cauchy-Schwarz inequality and $X_{t} \in \mathcal{S}_{+}^{d}(\mathbb{R})$, we obtain

$$
N_{T}^{n} \sum_{\tau_{i-1}^{n}<T}\left(\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}\right)^{2} \geq\left(\sum_{\tau_{i-1}^{n}<T} \Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}\right)^{2}
$$

The process $X_{t}$ is a.s. continuous on $[0, T)$, with $\sup _{t \in[0, T)}\left|X_{t}\right|<+\infty$ a.s., and thus the assumptions of Proposition 3.7 are satisfied for $(H, K)=(X, B)$. Therefore

$$
\sum_{\tau_{i}^{n}<T} \Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}} \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t .
$$

To summarize we have obtained that

$$
\liminf _{n \rightarrow+\infty}\left(N_{T}^{n}\left\langle Z^{n}\right\rangle_{T}-N_{T}^{n}\left(e_{0, T}^{n}+e_{1, T}^{n}+e_{2, T}^{n}+e_{3, T}^{n}\right)\right) \geq\left(\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t\right)^{2} \quad \text { a.s.. }
$$

To complete the proof, it is enough to show that $N_{T}^{n}\left(e_{0, T}^{n}+e_{1, T}^{n}+e_{2, T}^{n}+e_{3, T}^{n}\right) \xrightarrow{\text { a.s. }}$ 0 . In view of the assumption $\left(\mathbf{A}_{N}\right)$ it is sufficient to prove that

$$
\begin{equation*}
\varepsilon_{n}^{-2 \rho_{N}} e_{i, T}^{n} \xrightarrow{\text { a.s. }} 0 \quad \text { for } i=0,1,2,3 . \tag{4.7}
\end{equation*}
$$

Contribution $e_{0, T}^{n}$. Owing to Corollary 3.6, we obtain immediately that

$$
\left|e_{0, T}^{n}\right| \leq C_{0} \int_{0}^{T}\left|\Delta A_{t}\right|\left(\left|\Delta S_{t}\right|+\left|\Delta M_{t}\right|\right) \mathrm{d} t \leq C_{0} \varepsilon_{n}^{1+2 \alpha-\rho}
$$

for any $\rho>0$, which implies $\varepsilon_{n}^{-2 \rho_{N}} e_{0, T}^{n} \rightarrow 0$ since $\rho_{N}<\frac{1}{2}+\alpha$.
Contribution $e_{1, T}^{n}$. To handle it, we need the following lemma; its proof follows that of [GL14a, Lemma 3.2], with minor adaptations (see Appendix A.1).

Lemma 4.3. Under the assumptions $\left(\mathbf{H}_{A}\right),\left(\mathbf{H}_{M}\right),\left(\mathbf{H}_{v}\right)$, ( $\left.\mathbf{A}^{\text {osc. }}\right)$ and $\left(\mathbf{A}_{N}\right)$, we have $\varepsilon_{n}^{2-4 \rho_{N}}\left\langle R^{n}\right\rangle_{T} \xrightarrow{\text { a.s. }} 0$, where $R^{n}$ is defined in (4.3).

Now to show that $\varepsilon_{n}^{-2 \rho_{N}} e_{1, T}^{n} \rightarrow 0$, use the above lemma and ( $\left.\mathbf{A}_{M}^{\text {osc. }}\right)$ to get

$$
\varepsilon_{n}^{-2 \rho_{N}}\left|e_{1, T}^{n}\right| \leq \varepsilon_{n}^{-2 \rho_{N}}\left(\left\langle R^{n}\right\rangle_{T}+2 C_{0} \varepsilon_{n}\left(\left\langle R^{n}\right\rangle_{T}\right)^{1 / 2}=o\left(\varepsilon_{n}^{2 \rho_{N}-2}\right)+o(1) \xrightarrow{\text { a.s. }} 0 .\right.
$$

Contributions $e_{2, T}^{n}$ and $e_{3, T}^{n}$. The proof is similar to that of [GL14a, Theorem 3.1], we skip the details.

## 5 Optimal strategy

### 5.1 Preliminaries, pseudo-inverses

Now our main purpose is to provide, in notation of Theorem 4.2, an optimal discretization strategy, i.e. an admissible strategy $\mathcal{T}$ for which

$$
\lim _{n \rightarrow+\infty} N_{T}^{n}\left\langle Z^{n}\right\rangle_{T}=\left(\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t\right)^{2} \quad \text { a.s. }
$$

Notice that an existence result is proved in [GL14a, Theorem 3.3], only under the conditions that $\sigma$ is invertible, that $v(t, x)=\nabla_{x} u(t, x)$ with

$$
\inf _{0 \leq t<T} \lambda_{\min }\left(D_{x x}^{2} u\left(t, S_{t}\right)\right)>0 \quad \text { a.s. }
$$

and that $A=0$ (martingale case). Our aim here is to relax these three conditions, and to extend the ideas of this aforementioned theorem to our general setting.

Actually, the main difficulty comes from the possible degeneracy of $\sigma$. First recall the definition and some properties of pseudo-inverse matrix (a.k.a. Moore-Penrose generalized inverse).
Definition 2 (pseudo-inverse of a matrix). Let $\mathcal{M}$ be a real-valued $d \times d$ matrix. Consider the singular value decomposition of $\mathcal{M}$

$$
\mathcal{M}=U\left(\begin{array}{ll}
D & 0 \\
0 & 0
\end{array}\right) V^{\top}
$$

where $U, V$ are both orthogonal matrices, and $D$ is a diagonal matrix containing the (positive) singular values of $\mathcal{M}$ on its diagonal. Then the pseudo-inverse of $M$ is the $d \times d$ - matrix defined as

$$
\mathcal{M}^{\dagger}=V\left(\begin{array}{cc}
D^{-1} & 0 \\
0 & 0
\end{array}\right) U^{\top}
$$

We recall the following well-known properties, which can be easily checked from Definition 2:

$$
\left\{\begin{array}{l}
\mathcal{M} \mathcal{M}^{\dagger} \mathcal{M}=\mathcal{M}, \quad \mathcal{M}^{\dagger} \mathcal{M}^{\dagger} \mathcal{M}^{\dagger}=\mathcal{M}^{\dagger}  \tag{5.1}\\
\text { the matrices } \mathcal{M} \mathcal{M}^{\dagger} \text { and } \mathcal{M}^{\dagger} \mathcal{M} \text { are symmetric. }
\end{array}\right.
$$

### 5.2 Main result

We wish to design optimal stopping times in terms of the process $S$ to allow better tractability. Inspired by [GL14a], a good candidate is then the sequence $\left\{\mathcal{T}^{n}: n \geq 0\right\}$ where $\mathcal{T}^{n}$ is defined as:

$$
\left\{\begin{array}{l}
\tau_{0}^{n}:=0  \tag{5.2}\\
\tau_{i}^{n}:=\inf \left\{t>\tau_{i-1}^{n}:\left(S_{t}-S_{\tau_{i-1}^{n}}\right)^{\top} \Lambda_{\tau_{i-1}^{n}}\left(S_{t}-S_{\tau_{i-1}^{n}}\right) \geq \varepsilon_{n}^{2}\right\} \wedge T,
\end{array}\right.
$$

where $\Lambda_{t}:=\left(\sigma_{t}^{-1}\right)^{\top} X_{t} \sigma_{t}^{-1}$ with $X$ given by (4.2).
Such a sequence turns out to be optimal when $S$ is a martingale and under some additional assumptions (see [GL14a, Theorem 3.3]). The problems with this definition can arise if $\sigma_{t}$ is not invertible, or if $\Lambda_{t}$ is degenerate for some values of $t$ (then we have difficulties to verify ( $\left.\mathbf{A}^{\text {osc. }}\right)$ ). To overcome these problems we use $\sigma_{t}^{\dagger}$ instead of $\sigma_{t}^{-1}$. Furthermore we take $\Lambda_{t}^{(n)}$ equal to a small perturbation of $\Lambda_{t}$ depending on $\varepsilon_{n}$, such that $\Lambda_{t}^{(n)}$ is always non-degenerate.

We need one additional assumption.
$\left(\mathbf{H}_{\Lambda}\right)$ Let $\left(X_{t}\right)_{0 \leq t<T}$ be defined in (4.2) and consider the $\mathcal{S}_{+}^{d}(\mathbb{R})$-valued process defined by

$$
\Lambda_{t}:=\left(\sigma_{t}^{\dagger}\right)^{\top} X_{t} \sigma_{t}^{\dagger}, \quad \forall t \in[0, T)
$$

There exists a non-negative random variable $c_{(5.3)}$, finite a.s., such that

$$
\begin{equation*}
0 \leq \operatorname{Tr}\left(\Lambda_{t}\right) \leq c_{(5.3)}, \quad \forall t \in[0, T), \quad \text { a.s.. } \tag{5.3}
\end{equation*}
$$

Note that $\sigma^{\dagger}$ may be discontinuous, so $\Lambda$ may be too. Recall (see (3.14)) that $\chi($.$) stands for a smooth function such that \mathbf{1}_{(-\infty, 1 / 2]} \leq \chi(.) \leq \mathbf{1}_{(-\infty, 1]}$, and for $\mu>0$, we set $\chi_{\mu}(x)=\chi(x / \mu)$. Now we state the precise definition of an optimal sequence of strategies.

Theorem 5.1 (Optimal strategy). Assume that $\left(\mathbf{H}_{A}\right),\left(\mathbf{H}_{M}\right),\left(\mathbf{H}_{v}\right),\left(\mathbf{H}_{\Lambda}\right)$ are in force. Let $\rho_{N}$ satisfy (2.3) with $\rho_{N}>1$, and let $\delta \in\left(0,2\left(\rho_{N}-1\right)\right]$. For each $n \in \mathbb{N}$, define the process $\left(\Lambda_{t}^{(n)}: t<T\right)$ by

$$
\Lambda_{t}^{(n)}=\Lambda_{t}+\varepsilon_{n}^{\delta} \chi_{\varepsilon_{n}^{\delta}}\left(\lambda_{\min }\left(\Lambda_{t}\right)\right) \operatorname{Id}_{d}
$$

where $\Lambda$ is given in $\left(\mathbf{H}_{\Lambda}\right)$, and define the strategy $\mathcal{T}_{\varepsilon_{n}^{\delta}}^{n}$ by

$$
\left\{\begin{array}{l}
\tau_{0}^{n}:=0  \tag{5.4}\\
\tau_{i}^{n}:=\inf \left\{t>\tau_{i-1}^{n}:\left(S_{t}-S_{\tau_{i-1}^{n}}\right)^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)}\left(S_{t}-S_{\tau_{i-1}^{n}}\right) \geq \varepsilon_{n}^{2+\delta}\right\} \wedge T .
\end{array}\right.
$$

Then the sequence of strategies $\mathcal{T}=\left\{\mathcal{T}_{\varepsilon_{n}^{\delta}}^{n}: n \geq 0\right\}$ is admissible for the parameter $\rho_{N}$ and is asymptotically optimal, i.e.

$$
\lim _{n \rightarrow+\infty} N_{T}^{n}\left\langle Z^{n}\right\rangle_{T}=\left(\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t\right)^{2} \quad \text { a.s.. }
$$

To conclude this subsection, we provide a condition simpler than $\left(\mathbf{H}_{\Lambda}\right)$, the proof is postponed to the end of this section.

Proposition 5.2. Assume that $\left(\mathbf{H}_{A}\right),\left(\mathbf{H}_{M}\right),\left(\mathbf{H}_{v}\right)$ are in force, and assume that $v \in \mathcal{C}^{1,2}\left([0, T] \times \mathbb{R}^{d}\right)$ so that $D_{x} v_{t}$ and $X_{t}$ can be defined continuously up to $t=T$. If the matrix

$$
\begin{equation*}
C_{t}:=\sigma_{t}^{\top}\left(D_{x} v_{t}\right)^{\top} \sigma_{t} \neq 0 \tag{C}
\end{equation*}
$$

for all $t \in[0, T]$ a.s., then $\left(\mathbf{H}_{\Lambda}\right)$ holds.

### 5.3 Examples

### 5.3.1 About the assumptions $\left(\mathrm{H}_{\Lambda}\right)$ and $\left(\mathrm{H}_{C}\right)$

Recall that under our assumptions, $X$ is a.s. uniformly bounded on $[0, T)$. Thus in order to satisfy $\left(\mathbf{H}_{\Lambda}\right)$, it is enough to have $\sigma^{\dagger}$ a.s. uniformly bounded on $[0, T)$. We provide a (non-exhaustive) list of such examples.
a) $\sigma_{t}$ is invertible for any $t$ a.s.: then $\sigma_{t}^{\dagger}=\sigma_{t}^{-1}$ is clearly bounded on $[0, T]$.
b) We can also afford degenerate cases: for instance if $\sigma_{t}$ is constant in time (but possibly with $\operatorname{rank}\left(\sigma_{t}\right)<d$ ), then $\sigma_{t}^{\dagger}$ is also constant in time (and thus bounded).
c) The previous principle can be generalized to the time-dependent case $\sigma_{t}=$ $\left(\begin{array}{cc}\Sigma_{t} & 0 \\ 0 & 0\end{array}\right)$ where $\Sigma_{t}$ is a square matrix, a.s. invertible at any time: indeed $\sigma_{t}^{\dagger}=\left(\begin{array}{cc}\Sigma_{t}^{-1} & 0 \\ 0 & 0\end{array}\right)$ is bounded on $[0, T]$.

Now, we argue that checking $\left(\mathbf{H}_{C}\right)$ may be sometimes much simpler than the verification of $\left(\mathbf{H}_{\Lambda}\right)$. Let us give a non-trivial example where $\sigma^{\dagger}$ is not continuous a.s. For the $i$-th component of $S$, take a squared $\delta_{i}$-dimensional radial OrnsteinUhlenbeck process with parameter $-\lambda_{i}$, which is the strong solution to

$$
S_{t}^{i}=S_{0}^{i}+\int_{0}^{t}\left(\delta_{i}-\lambda_{i} S_{s}^{i}\right) \mathrm{d} s+2 \int_{0}^{t} \sqrt{S_{s}^{i}} \mathrm{~d} B_{s}^{i}
$$

where $S_{0}^{i}>0, \delta_{i} \geq 0, \lambda_{i} \in \mathbb{R}$ (see [GJY03]). The matrix $\sigma_{t}$ is diagonal and its $i$-th element is equal to $2 \sqrt{S_{t}^{i}}$. It is easy to check that $\left(\mathbf{H}_{A}\right)$ and $\left(\mathbf{H}_{M}\right)$ hold (in particular $\sigma_{t} \neq 0$ for all $t$ a.s.). The pseudo-inverse $\sigma_{t}^{\dagger}$ is diagonal with $i$-th element equal to $\left[2 \sqrt{S_{t}^{i}}\right]^{-1} \mathbf{1}_{S_{t}^{i}>0}$. Assume now that one of the $\delta_{i}$ is strictly smaller than 2: then the associated component $S^{i}$ has a positive probability to hit 0 before $T$. As a consequence, with positive probability, $\sigma^{\dagger}$ is unbounded on $[0, T]$ and it is not clear anymore to check directly $\left(\mathbf{H}_{\Lambda}\right)$. Alternatively, assume (again to simplify) that $D_{x} v_{t} \in \mathcal{S}_{++}^{d}(\mathbb{R})$. Then $C_{t} \neq 0$ : indeed, $C_{t} \in \mathcal{S}_{+}^{d}(\mathbb{R})$ and $\operatorname{Tr}\left(C_{t}\right)=\operatorname{Tr}\left(D_{x} v_{t} \sigma_{t} \sigma_{t}^{\top}\right)>0$ since $\sigma_{t} \sigma_{t}^{\top} \neq 0$ and $D_{x} v_{t}$ is invertible.

### 5.3.2 A numerical example

We consider a two-dimensional example, defined by

$$
S_{t}=\binom{B_{t}^{1}+0.3 B_{t}^{2}}{\int_{0}^{t} B_{s}^{1} \mathrm{~d} s}
$$

It corresponds to a constant (degenerate) matrix

$$
\sigma_{t}=\left(\begin{array}{cc}
1 & 0.3 \\
0 & 0
\end{array}\right)
$$

For the function $v$ we take

$$
v(t, x)=\binom{\cos \left(3 x_{1}\right)}{\cos \left(3 x_{2}\right)}
$$

and we set $T=1$. According to the previous paragraph, $\left(\mathbf{H}_{\Lambda}\right)$ is satisfied and an optimal sequence of strategies is given by Theorem 5.1. To assess the efficiency of an arbitrary admissible sequence of strategies we set

$$
\alpha_{n}:=\frac{N_{T}^{n}\left\langle Z^{n}\right\rangle_{T}}{\left(\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t\right)^{2}} \quad \text { and } \quad \beta_{n}:=\sqrt{N_{T}^{n}} Z_{T}^{n}
$$

From Theorem 4.2 we must have $\lim _{\inf }^{n \rightarrow+\infty}{ }^{2} \geqslant 1$ a.s., while for the optimal sequence the equality holds. The normalized error $\beta_{n}$ is also important in practice, however we cannot in general asymptotically control a.s. this quantity. But it is easy to believe that the values of $\beta_{n}$ are smaller for strategies where the corresponding values of $\alpha_{n}$ are smaller, at least in mean. We will illustrate this heuristics in the following.

Namely, we denote by $\alpha_{n, \text { opt }}, \beta_{n, \text { opt }}$ the values of $\alpha_{n}, \beta_{n}$ for the optimal strategy defined in Theorem 5.1, for several simulations. For a given number of grid times $N_{T}^{n}$ of the optimal strategy, we also consider the deterministic strategy with $N_{T}^{n}$ equidistant times and denote by $\alpha_{n, d e t}, \beta_{n, d e t}$ the values of $\alpha_{n}, \beta_{n}$ for this strategy. This way of proceeding is aimed at comparing the performance of these two strategies with the same number of time points.

To compute the hitting times we use a thin uniform time mesh with $\bar{n}=$ 10000 points. Figure 1 shows the pairs $\left(\alpha_{n, \text { opt }}, \beta_{n, \text { opt }}\right)$ and $\left(\alpha_{n, \text { det }}, \beta_{n, \text { det }}\right)$ for ten simulations, with $\varepsilon_{n}=0.04$ and $\varepsilon_{n}^{\delta}=0.1$. As expected from Theorems 4.2 and 5.1, we observe the inequality $\alpha_{n, o p t}<\alpha_{n, \text { det }}$ and the limit $\alpha_{n, o p t} \approx 1$. Moreover, the inequality $\left|\beta_{n, \text { opt }}\right|<\left|\beta_{n, \text { det }}\right|$ holds as well for most of the simulations.


Figure 1: The pairs $\left(\alpha_{n, \text { det }}, \beta_{n, \text { det }}\right)$ and $\left(\alpha_{n, \text { opt }}, \beta_{n, \text { opt }}\right)$ are represented by squares and circles respectively.

### 5.4 Proof of Theorem 5.1

The proof is divided into several steps. Assumptions of Theorem 5.1 are in force in all this subsection.

### 5.4.1 Step 1: a reverse relation between $X$ and $\Lambda$

Proposition 5.3. The following equality holds

$$
\begin{equation*}
X_{t}=\left(\sigma_{t}\right)^{\top} \Lambda_{t} \sigma_{t}, \quad \forall t \in[0, T) \quad \text { a.s.. } \tag{5.5}
\end{equation*}
$$

Proof. We are going to establish the above relation for any given $t$, with probability 1: however, the reader can check that the negligible set can be the same for all $t$ (as for the definitions of $\sigma, X, \Lambda$ ) because the arguments used are of deterministic nature.

If $\sigma_{t}$ is invertible, $\sigma_{t}^{\dagger}=\sigma_{t}^{-1}$ and obviously $X_{t}=\left(\sigma_{t}\right)^{\top} \Lambda_{t} \sigma_{t}$ in view of the definition $\left(\mathbf{H}_{\Lambda}\right)$.

Now assume that $\operatorname{rank}\left(\sigma_{t}\right)<d$. By (5.1) we have

$$
\begin{equation*}
\sigma_{t} \sigma_{t}^{\dagger} \sigma_{t}=\sigma_{t} \tag{5.6}
\end{equation*}
$$

and the matrix $\sigma_{t}^{\dagger} \sigma_{t}$ is symmetric. We choose an orthonormal basis $\left(e_{i}\right)_{1 \leq i \leq d}$ under which the matrix $\sigma_{t}^{\dagger} \sigma_{t}$ is diagonal, i.e.

$$
\sigma_{t}^{\dagger} \sigma_{t}=\left(\begin{array}{cccc}
\alpha_{1} & 0 & \ldots & 0 \\
0 & \alpha_{2} & \ldots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \ldots & \alpha_{d}
\end{array}\right)
$$

for some $\alpha_{1}, \ldots, \alpha_{d}$. If $\sigma_{t}^{1}, \ldots, \sigma_{t}^{d}$ are the column vectors of $\sigma_{t}$ (in the basis $\left.\left(e_{i}\right)_{1 \leq i \leq d}\right)$, then from (5.6) we get

$$
\begin{equation*}
\left(\alpha_{1} \sigma_{t}^{1}, \ldots, \alpha_{d} \sigma_{t}^{d}\right)=\left(\sigma_{t}^{1}, \ldots, \sigma_{t}^{d}\right) \tag{5.7}
\end{equation*}
$$

For any $1 \leq i \leq d$ if $\sigma_{t}^{i} \neq 0$ then we must have $\alpha_{i}=1$. On the other hand $k:=\operatorname{rank}\left(\sigma_{t}^{\dagger} \sigma_{t}\right) \leq \operatorname{rank}\left(\sigma_{t}\right)<d$. Hence by permuting the basis elements and using (5.6) we can write $\sigma_{t}^{\dagger} \sigma_{t}$ and $\sigma_{t}$ in the form:

$$
\sigma_{t}^{\dagger} \sigma_{t}=\left(\begin{array}{cc}
\operatorname{Id}_{k} & 0  \tag{5.8}\\
0 & 0
\end{array}\right), \quad \sigma_{t}=\left(\begin{array}{cccccc}
\sigma_{1, t}^{1} & \ldots & \sigma_{1, t}^{k} & 0 & \ldots & 0 \\
\sigma_{2, t}^{1} & \ldots & \sigma_{2, t}^{k} & 0 & \ldots & 0 \\
\vdots & \ldots & \vdots & \vdots & \ldots & \vdots \\
\sigma_{d, t}^{t} & \ldots & \sigma_{d, t}^{k} & 0 & \ldots & 0
\end{array}\right)
$$

We want to show that $X_{t}=\left(\sigma_{t}\right)^{\top} \Lambda_{t} \sigma_{t}$ which by the definition of $\Lambda_{t}$ is equivalent to

$$
\begin{equation*}
X_{t}=\left(\sigma_{t}^{\dagger} \sigma_{t}\right)^{\top} X_{t}\left(\sigma_{t}^{\dagger} \sigma_{t}\right)=\left(\sigma_{t}^{\dagger} \sigma_{t}\right) X_{t}\left(\sigma_{t}^{\dagger} \sigma_{t}\right) \tag{5.9}
\end{equation*}
$$

In view of (5.8) and since $X$ is symmetric non-negative definite, the equality (5.9) is equivalent to the following system of equations:

$$
\begin{equation*}
e_{i}^{\top} X_{t} e_{i}=0 \quad \text { for } \quad i=k+1, \ldots, d \tag{5.10}
\end{equation*}
$$

where $\left(e_{i}\right)$ are the vectors of the basis. We now prove (5.10). Let $i \in\{k+$ $1, \ldots, d\}$. From the definition of $X_{t}$ we get

$$
\begin{equation*}
2 \operatorname{Tr}\left(X_{t}\right) X_{t}+4 X_{t}^{2}=\sigma_{t}^{\top} \tilde{C}_{t} \sigma_{t} \tag{5.11}
\end{equation*}
$$

where $\tilde{C}_{t}=\left(D_{x} v_{t}\right)^{\top} \sigma_{t} \sigma_{t}^{\top} D_{x} v_{t}$. From (5.8) it is clear that $\sigma_{t} e_{i}=0$, thus Equation (5.11) yields

$$
2 \operatorname{Tr}\left(X_{t}\right) e_{i}^{\top} X_{t} e_{i}+4 e_{i}^{\top} X_{t}^{2} e_{i}=0
$$

Both $X_{t}$ and $X_{t}^{2}$ are in $\mathcal{S}_{+}^{d}(\mathbb{R})$, thus both above terms are non-negative, therefore they are equal to 0 . Either $\operatorname{Tr}\left(X_{t}\right)=0$ (implying $X_{t}=0$ and (5.10)), or $\operatorname{Tr}\left(X_{t}\right)>0$ and $e_{i}^{\top} X_{t} e_{i}=0$. In any case, (5.10) holds and we are done.

### 5.4.2 Step 2: verification of ( $\left.\mathrm{A}_{S}^{\text {osc. }}\right)$

The stopping times (5.4) define a sequence of strategy satisfying ( $\left.\mathbf{A}_{S}^{\text {osc. }}\right)$ : this is a consequence of Theorem 3.10-(i) with $H=\Lambda$. Indeed the existence of the finite random variable $C_{H}$ stems from (5.3).

### 5.4.3 Step 3: verification of $\left(\mathbf{A}_{N}\right)$

We aim at showing
Proposition 5.4. We have the following convergence

$$
\sum_{\tau_{i-1}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}} \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(\Lambda_{t} \mathrm{~d}\langle M\rangle_{t}\right)=\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t .
$$

Then, in view of Theorem 3.10-(ii), we conclude that the sequence of strategies $\mathcal{T}=\left\{\mathcal{T}_{\varepsilon_{n}^{\delta}}^{n}: n \geq 0\right\}$ satisfies $\left(\mathbf{A}_{N}\right)$. Combined with Step 2, we have proved that this is an admissible sequence.

Observe that the above result is not a particular case of Proposition (3.7) since we do not know if $\Lambda$ is continuous in time (it is likely not for degenerate $\sigma)$. To handle this difficulty, we are going to leverage the reverse relation between $X$ and $\Lambda$ (Step 1), and the continuity of $X$.

Proof of Proposition 5.4. By Itô's lemma like for (3.12) and using that $\Lambda$ is symmetric, we obtain

$$
\begin{equation*}
\sum_{\tau_{i-1}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}=2 \int_{0}^{T} \Delta S_{t}^{\top} \Lambda_{\phi(t)} \mathrm{d} S_{t}+\int_{0}^{T} \operatorname{Tr}\left(\Lambda_{\phi(t)} \mathrm{d}\langle M\rangle_{t}\right) \tag{5.12}
\end{equation*}
$$

Then

$$
\begin{aligned}
\int_{0}^{T} \operatorname{Tr}\left(\Lambda_{\phi(t)} \mathrm{d}\langle M\rangle_{t}\right) & =\int_{0}^{T} \operatorname{Tr}\left(\sigma_{t}^{\top} \Lambda_{\phi(t)} \sigma_{t}\right) \mathrm{d} t=\int_{0}^{T} \operatorname{Tr}\left(\sigma_{\phi(t)}^{\top} \Lambda_{\phi(t)} \sigma_{\phi(t)}\right) \mathrm{d} t \\
& +\int_{0}^{T} \operatorname{Tr}\left(\left(\sigma_{t}-\sigma_{\phi(t)}\right)^{\top} \Lambda_{\phi(t)}\left(\sigma_{t}+\sigma_{\phi(t)}\right)\right) \mathrm{d} t
\end{aligned}
$$

Observe that the first term on the r.h.s. above is equal to $\int_{0}^{T} \operatorname{Tr}\left(X_{\phi(t)}\right) \mathrm{d} t$ owing to Proposition 5.3: since $X$ is a.s. bounded continuous and the time step goes to 0 (see (3.7) valid under $\left(\mathbf{A}_{S}^{\text {osc. }}\right)$ ), we easily obtain $\int_{0}^{T} \operatorname{Tr}\left(X_{\phi(t)}\right) \mathrm{d} t \xrightarrow{\text { a.s. }}$ $\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t$.

The second term tends to 0 a.s. thanks to the continuity of $\sigma$ and the uniform bound (5.3) on $\Lambda$. We have proved

$$
\int_{0}^{T} \operatorname{Tr}\left(\Lambda_{\phi(t)} \mathrm{d}\langle M\rangle_{t}\right) \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t .
$$

To complete the proof, in view of (5.12) it remains to show that

$$
\int_{0}^{T} \Delta S_{t}^{\top} \Lambda_{\phi(t)} \mathrm{d} S_{t} \xrightarrow{\text { a.s. }} 0 .
$$

The a.s.-convergence to 0 of the contribution $\int_{0}^{T} \Delta S_{t}^{\top} \Lambda_{\phi(t)} \mathrm{d} A_{t}$ is proved as for (3.13), using ( $\mathbf{A}_{S}^{\text {osc. . }}$ ) and $\left(\mathbf{H}_{\Lambda}\right)$. The second contribution $K_{T}^{n}:=\int_{0}^{T} \Delta S_{t}^{\top} \Lambda_{\phi(t)} \mathrm{d} M_{t}$ is a local martingale, which bracket is bounded by $\varepsilon_{n}^{2}$ up to a random finite constant (use again ( $\mathbf{A}_{S}^{\text {osc. }}$ ) and $\left(\mathbf{H}_{\Lambda}\right)$ ). Consequently, an application of Lemma 3.1 with $p=2$, ensures that $K_{T}^{n} \xrightarrow{\text { a.s. }} 0$. We are done.

### 5.4.4 Final step: completion of proof of Theorem 5.1

So far, we have showed that the strategy $\mathcal{T}=\left\{\mathcal{T}_{\varepsilon_{n}^{\delta}}^{(n)}: n \geq 0\right\}$ is admissible. We now prove that

$$
\lim _{n \rightarrow+\infty} N_{T}^{n}\left\langle Z^{n}\right\rangle_{T}=\left(\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t\right)^{2} \quad \text { a.s.. }
$$

First, proceeding as (3.16), we write that $\varepsilon_{n}^{2+\delta} N_{T}^{n}$ equals

$$
\begin{equation*}
\varepsilon_{n}^{2+\delta}+\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}+\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top}\left(\Lambda_{\tau_{i-1}^{n}}^{(n)}-\Lambda_{\tau_{i-1}^{n}}\right) \Delta S_{\tau_{i}^{n}} \tag{5.13}
\end{equation*}
$$

The first term converges to 0 , as well as the last term (proceeding as for (3.17)), while the second one converges a.s. to $\int_{0}^{T} \operatorname{Tr}\left(\Lambda_{t} \mathrm{~d}\langle M\rangle_{t}\right)$ (Proposition 5.4). To summarize, we have justified

$$
\begin{equation*}
\lim _{n \rightarrow+\infty} \varepsilon_{n}^{2+\delta} N_{T}^{n}=\int_{0}^{T} \operatorname{Tr}\left(\Lambda_{t} \mathrm{~d}\langle M\rangle_{t}\right)=\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t \quad \text { a.s.. } \tag{5.14}
\end{equation*}
$$

Thus it remains to show that

$$
\begin{equation*}
\lim _{n \rightarrow+\infty} \varepsilon_{n}^{-(2+\delta)}\left\langle Z^{n}\right\rangle_{T}=\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t \quad \text { a.s.. } \tag{5.15}
\end{equation*}
$$

Starting from (4.6), write $\left\langle Z^{n}\right\rangle_{T}$ in the form

$$
\left\langle Z^{n}\right\rangle_{T}=\sum_{\tau_{i-1}^{n}<T}\left(\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)} \Delta S_{\tau_{i}^{n}}\right)^{2}+e_{0, T}^{n}+e_{1, T}^{n}+e_{2, T}^{n}+e_{3, T}^{n}+e_{4, T}^{n}+e_{5, T}^{n},
$$

where $e_{0, T}^{n}, e_{1, T}^{n}, e_{2, T}^{n}, e_{3, T}^{n}$ are defined as in the proof of Theorem 4.2 and the other terms are defined as follows:

$$
\begin{aligned}
& e_{4, T}^{n}:=\sum_{\tau_{i-1}^{n}<T}\left(\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}\right)^{2}-\sum_{\tau_{i-1}^{n}<T}\left(\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}\right)^{2}, \\
& e_{5, T}^{n}:=\sum_{\tau_{i-1}^{n}<T}\left(\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}\right)^{2}-\sum_{\tau_{i-1}^{n}<T}\left(\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)} \Delta S_{\tau_{i}^{n}}\right)^{2} .
\end{aligned}
$$

First notice that for each $i \leq N_{T}^{n}-1$ we have $\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)} \Delta S_{\tau_{i}^{n}}=\varepsilon_{n}^{2+\delta}$, thus

$$
\begin{aligned}
& \varepsilon_{n}^{-(2+\delta)} \sum_{\tau_{i-1}^{n}<T}\left(\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)} \Delta S_{\tau_{i}^{n}}\right)^{2} \\
& =\sum_{\tau_{i}^{n}<T} \Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)} \Delta S_{\tau_{i}^{n}}+\varepsilon_{n}^{-(2+\delta)}\left(\Delta S_{T}^{\top} \Lambda_{\tau_{N T-1}^{n}}^{(n)} \Delta S_{T}\right)^{2} \\
& \xrightarrow{\text { a.s. }} \int_{0}^{T} \operatorname{Tr}\left(\Lambda_{t} \mathrm{~d}\langle M\rangle_{t}\right)=\int_{0}^{T} \operatorname{Tr}\left(X_{t}\right) \mathrm{d} t,
\end{aligned}
$$

where the last convergence is derived similarly to that of (5.13).
Moreover, from (4.7) in the proof of Theorem 4.2, we already have (for $\varepsilon_{n}$ small enough so that $\varepsilon_{n} \leq 1$ and since $2+\delta \leq 2 \rho_{N}$ )

$$
\varepsilon_{n}^{-(2+\delta)} e_{i, T}^{n} \leq \varepsilon_{n}^{-2 \rho_{N}} e_{i, T}^{n} \xrightarrow{\text { a.s. }} 0 \quad \text { a.s. for } i=0,1,2,3 .
$$

To complete the proof of Theorem 5.1, it remains only to prove that

$$
\varepsilon_{n}^{-(2+\delta)} e_{i, T}^{n} \xrightarrow{\text { a.s. }} 0 \quad \text { a.s. for } i=4,5 \text {. }
$$

We start with $e_{5, T}^{n}$ :

$$
\begin{aligned}
\left|\varepsilon_{n}^{-(2+\delta)} e_{5, T}^{n}\right| \leq & \sum_{\tau_{i-1}^{n}<T}\left(\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}+\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}}^{(n)} \Delta S_{\tau_{i}^{n}}\right) \\
& \times\left|\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}-\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)} \Delta S_{\tau_{i}^{n}}\right| \varepsilon_{n}^{-(2+\delta)} \\
\leq & \sum_{\tau_{i-1}^{n}<T} \varepsilon_{n}^{\delta} \chi_{\varepsilon_{n}^{\delta}}\left(\lambda_{\min }\left(\Lambda_{\tau_{i-1}^{n}}\right)\right)\left|\Delta S_{\tau_{i}^{n}}\right|^{2}\left|2 \varepsilon_{n}^{-2-\delta} \Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}}^{(n)} \Delta S_{\tau_{i}^{n}}\right| \\
\leq & 2 \varepsilon_{n}^{\delta} \sum_{\tau_{i-1}^{n}<T}\left|\Delta S_{\tau_{i}^{n}}\right|^{2} \xrightarrow{\text { a.s. }} 0
\end{aligned}
$$

thanks to Proposition 3.8.
Finally, we analyse $e_{4, T}^{n}$. From its definition, Proposition 5.3 and $\left(\mathbf{H}_{\Lambda}\right)$, we get

$$
\begin{align*}
& \left|\varepsilon_{n}^{-(2+\delta)} e_{4, T}^{n}\right| \\
& \leq \varepsilon_{n}^{-(2+\delta)} \sum_{\tau_{i-1}^{n}<T}\left|\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}-\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}\right|\left(\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}+\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}\right) \\
& \leq \varepsilon_{n}^{-(2+\delta)} c_{(5.3)} \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\Delta S_{t}+\sigma_{\phi(t)} \Delta B_{t}\right|\left|\int_{\phi(t)}^{t} \Delta \sigma_{s} \mathrm{~d} B_{s}+\Delta A_{t}\right| \\
& \quad \times\left(\Delta B_{\tau_{i}^{n}}^{\top} X_{\tau_{i-1}^{n}} \Delta B_{\tau_{i}^{n}}+\Delta S_{\tau_{i}^{n}}^{\top} \Lambda_{\tau_{i-1}^{n}} \Delta S_{\tau_{i}^{n}}\right) \tag{5.16}
\end{align*}
$$

Now we apply twice Lemma 3.3-(ii), first taking $\theta=0$ and second taking $\theta=\theta_{\sigma}$ : it readily follows that for any given $\rho>0$, we have a.s. for any $n \in \mathbb{N}$

$$
\begin{align*}
& \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left(\left|\Delta M_{t}\right|+\left|\sigma_{\phi(t)} \Delta B_{t}\right|\right) \leq C_{0} \varepsilon_{n}^{1-\rho},  \tag{5.17}\\
& \sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\int_{\phi(t)}^{t} \Delta \sigma_{s} \mathrm{~d} B_{s}\right| \leq C_{0} \varepsilon_{n}^{1+\theta_{\sigma}-\rho} \tag{5.18}
\end{align*}
$$

Moreover by Corollary 3.6 we have

$$
\sup _{1 \leq i \leq N_{T}^{n}} \sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\Delta A_{t}\right| \leq C_{0} \varepsilon_{n}^{2 \alpha-\rho}
$$

The last factor in the r.h.s. of (5.16) converges a.s. to a finite random variable (Propositions 3.7 and 5.4). Combining this with the above estimates, the inequality (5.16) becomes

$$
\left|\varepsilon_{n}^{-(2+\delta)} e_{4, T}^{n}\right| \leq C_{0} \varepsilon_{n}^{-2-\delta} \varepsilon_{n}^{1-\rho}\left(\varepsilon_{n}^{1+\theta_{\sigma}-\rho}+\varepsilon_{n}^{2 \alpha-\rho}\right)
$$

It is now easy to see that, since we have chosen $\delta<\theta_{\sigma}$ and $\delta<2 \alpha-1$, we can take $\rho$ small enough so that $\varepsilon_{n}^{-(2+\delta)} e_{4, T}^{n} \rightarrow 0$. The proof is finished.

### 5.5 Proof of Proposition 5.2

Consider the equation solved by $X_{t}$ (see (4.1) and (4.2)), and multiply it by $\sigma_{t}^{\dagger}$ from the right and by $\left(\sigma_{t}^{\dagger}\right)^{\top}$ from the left: it gives

$$
2 \operatorname{Tr}\left(X_{t}\right)\left(\sigma_{t}^{\dagger}\right)^{\top} X_{t} \sigma_{t}^{\dagger}+4\left(\sigma_{t}^{\dagger}\right)^{\top} X_{t}^{2} \sigma_{t}^{\dagger}=\left(\sigma_{t} \sigma_{t}^{\dagger}\right)^{\top} \tilde{C}_{t}\left(\sigma_{t} \sigma_{t}^{\dagger}\right)
$$

where $\tilde{C}_{t}=\left(D_{x} v_{t}\right)^{\top} \sigma_{t} \sigma_{t}^{\top} D_{x} v_{t}$. Take the trace, use that $\left(\sigma_{t}^{\dagger}\right)^{\top} X_{t}^{2} \sigma_{t}^{\dagger} \in \mathcal{S}_{+}^{d}(\mathbb{R})$ and $\left(\mathrm{H}_{\Lambda}\right)$, in order to obtain

$$
2 \operatorname{Tr}\left(X_{t}\right) \operatorname{Tr}\left(\Lambda_{t}\right) \leq \operatorname{Tr}\left(\left(\sigma_{t} \sigma_{t}^{\dagger}\right)^{\top} \tilde{C}_{t}\left(\sigma_{t} \sigma_{t}^{\dagger}\right)\right)
$$

Recall the inequality $\operatorname{Tr}\left(\mathcal{S} \mathcal{S}^{\prime}\right) \leq \operatorname{Tr}(\mathcal{S}) \operatorname{Tr}\left(\mathcal{S}^{\prime}\right)$ for any non-negative definite symmetric matrices $\mathcal{S}$ and $\mathcal{S}^{\prime}$. Thus, $\operatorname{Tr}\left(\left(\sigma_{t} \sigma_{t}^{\dagger}\right)^{\top} \tilde{C}_{t}\left(\sigma_{t} \sigma_{t}^{\dagger}\right)\right) \leq d^{2} \operatorname{Tr}\left(\tilde{C}_{t}\right)$ where we have used the easy inequality $\operatorname{Tr}\left(\sigma_{t} \sigma_{t}^{\dagger}\right) \leq d$. Note that the above inequalities are of deterministic nature and therefore they hold for any $t$ with probability 1 (the full set is the one allowing to define $X, \Lambda, \sigma, \tilde{C})$. Invoking $\left(\mathbf{H}_{M}\right)$ and $\left(\mathbf{H}_{v}\right)$ to control $\tilde{C}$, we deduce that there exists a non-negative random variable $\tilde{c}$, finite a.s., such that

$$
\begin{equation*}
\operatorname{Tr}\left(X_{t}\right) \operatorname{Tr}\left(\Lambda_{t}\right) \leq \tilde{c}, \quad \forall t \in[0, T] \quad \text { a.s.. } \tag{5.19}
\end{equation*}
$$

Owing to the condition $\left(\mathbf{H}_{C}\right), X_{t} \neq 0$ for any $t \in[0, T]$ a.s., and by continuity of $X_{t}$, we get that $\inf _{t \in[0, T]} \operatorname{Tr}\left(X_{t}\right)>0$ a.s. and we conclude to $\left(\mathbf{H}_{\Lambda}\right)$ thanks to (5.19).

## A Appendix

## A. 1 Proof of the Lemma 4.3

In view of $\left(\mathbf{H}_{v}\right)$ there exists $\Omega_{\mathcal{D}}$ with $\mathbb{P}\left(\Omega_{\mathcal{D}}\right)=1$ such that for every $\omega \in \Omega_{\mathcal{D}}$ there is $\delta(\omega)>0$ such that, for any $\mathcal{A} \in\left\{D_{x_{j}}, D_{x_{j} x_{k}}^{2}, D_{t}: 1 \leq j, k \leq d\right\}$,

$$
\sup _{0 \leq t<T} \sup _{\left|x-S_{t}(\omega)\right| \leq \delta(\omega)}|\mathcal{A} v(t, x)|<+\infty
$$

Since $\sup _{1 \leq i \leq N_{T}^{n}} \Delta \tau_{i}^{n} \xrightarrow{\text { a.s. }} 0$ and $S$ is continuous on $[0, T]$, there exists a set $\Omega_{\mathcal{C}}$ of full measure such that, for every $\omega \in \Omega_{\mathcal{C}}$, for $n$ large enough we have

$$
\sup _{0 \leq s, t \leq T,|t-s| \leq \sup _{1 \leq i \leq N_{T}^{n}} \Delta \tau_{i}^{n}}\left|S_{t}-S_{s}\right| \leq \delta(\omega) .
$$

Hence for $\omega \in \Omega_{\mathcal{C}} \cap \Omega_{\mathcal{D}}$, for $n$ large enough, by a Taylor formula we obtain

$$
\sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|v\left(t, S_{t}\right)-v\left(\tau_{i-1}^{n}, S_{\tau_{i-1}^{n}}\right)-D_{x} v\left(\tau_{i-1}^{n}, S_{\tau_{i-1}^{n}}\right)\right| \leq C_{0}\left(\Delta \tau_{i}^{n}+\sup _{t \in\left(\tau_{i-1}^{n}, \tau_{i}^{n}\right]}\left|\Delta S_{t}\right|^{2}\right)
$$

Plugging this estimate into $\left\langle R^{n}\right\rangle_{T}$ we obtain that a.s., for $n$ large enough,

$$
\varepsilon_{n}^{2-4 \rho_{N}}\left\langle R^{n}\right\rangle_{T} \leq C_{0} \varepsilon_{n}^{2-4 \rho_{N}} \sum_{\tau_{i-1}^{n}<T}\left(\left(\Delta \tau_{i}^{n}\right)^{3}+\Delta \tau_{i}^{n} \sup _{\tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}}\left|\Delta S_{t}\right|^{4}\right)
$$

We deduce that $\varepsilon_{n}^{2-4 \rho_{N}}\left\langle R^{n}\right\rangle_{T} \xrightarrow{\text { a.s. }} 0$ since

- for any $\rho>0, \varepsilon_{n}^{2-4 \rho_{N}} \sum_{\tau_{i-1}^{n}<T}\left(\Delta \tau_{i}^{n}\right)^{3} \leq \varepsilon_{n}^{2-4 \rho_{N}} N_{T}^{n} \sup _{1 \leq i \leq N_{T}}\left(\Delta \tau_{i}^{n}\right)^{3} \leq$ $C_{0} \varepsilon_{n}^{8-6 \rho_{N}-\rho}$ by using Lemma 3.2-(ii), thus it converges to 0 since $\rho_{N}<$ $4 / 3$,
- $\varepsilon_{n}^{2-4 \rho_{N}} \sum_{\tau_{i-1}^{n}<T} \Delta \tau_{i}^{n} \sup _{\tau_{i-1}^{n} \leq t \leq \tau_{i}^{n}}\left|\Delta S_{t}\right|^{4} \leq C_{0} \varepsilon_{n}^{6-4 \rho_{N}} T \rightarrow 0 \quad$ a.s..

We are done.

## A. 2 Almost sure convergence using domination in expectation

The next result allows to prove the a.s. convergence of a dominated process $U$ using that of a dominating process $V$, the domination relation being in expectation. Its use is crucial in our analysis.

Lemma A. 1 ([GL14a, Lemma 2.2]). Let $\mathcal{C}_{0}^{+}$be the set of non-negative continuous adapted processes, vanishing at $t=0$. Let $\left(U^{n}\right)_{n \geq 0}$ and $\left(V^{n}\right)_{n \geq 0}$ be two sequences of processes in $\mathcal{C}_{0}^{+}$. Assume that
(i) $t \mapsto V_{t}^{n}$ is a non-decreasing function on $[0, T]$, a.s.;
(ii) the series $\sum_{n \geq 0} V_{T}^{n}$ converges a.s.;
(iii) there is a constant $c \geq 0$ such that, for every $n \in \mathbb{N}, k \in \mathbb{N}$ and $t \in[0, T]$, we have

$$
\mathbb{E}\left[U_{t \wedge \theta_{k}}^{n}\right] \leq c \mathbb{E}\left[V_{t \wedge \theta_{k}}^{n}\right]
$$

with the stopping time $\theta_{k}:=\inf \left\{s \in[0, T]: \bar{V}_{s} \geq k\right\}^{1}$ setting $\bar{V}_{t}=$ $\sum_{n \geq 0} V_{t}^{n}$.
Then for any $t \in[0, T]$, the series $\sum_{n \geq 0} U_{t}^{n}$ converges a.s.. As a consequence, $U_{t}^{n} \xrightarrow{\text { a.s. }} 0$.

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[^1]:    ${ }^{1}$ with the usual convention $\inf \emptyset=+\infty$.

